

GERB Operations Report

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GIST 36 – ECMWF, 18th Oct 2016

Introduction

GERB-3

- Recap recovery from stuck despin mirror
- Summarise effect of ~21 month outage on mirror face
- DSM performance since recovery

GERB-4

- Commissioning including early spin rate problems
- In orbit storage activation operations

GERB-1

- Despin mirror bearing end of life

GERB-2

- Move to 41.5°E
- Limited drift data and issues with ESU/SOL

GERB-3 Recovery Overview

GERB-3 Test 22 involved three distinct sections:

- Power Cycling

In order to try to find a more favourable starting position a power cycle was necessary. The first significant position change was generated by a power cycle on 21/01/15 but the position this position (202.46°) was worse than before (36.8°)

- Position Testing

With the despin drive disabled coarse phase commands were used to isolate which of the 50 sectors the uninitialized pitch counter was reading.

- Enabling Patch 308

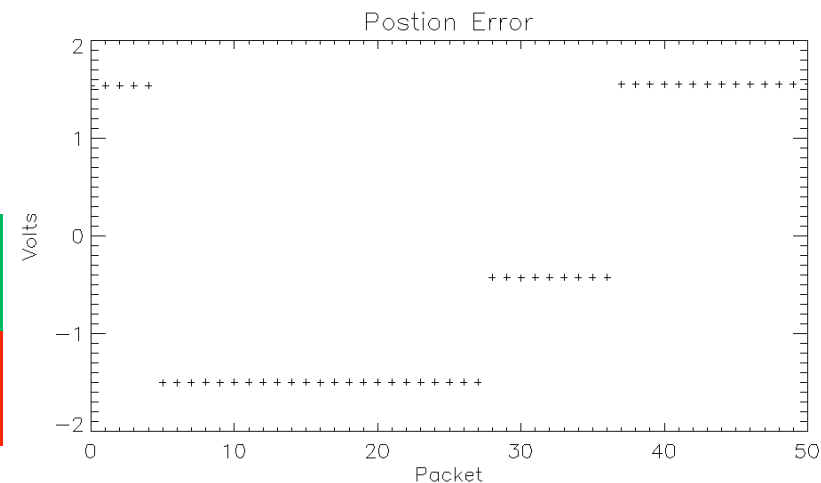
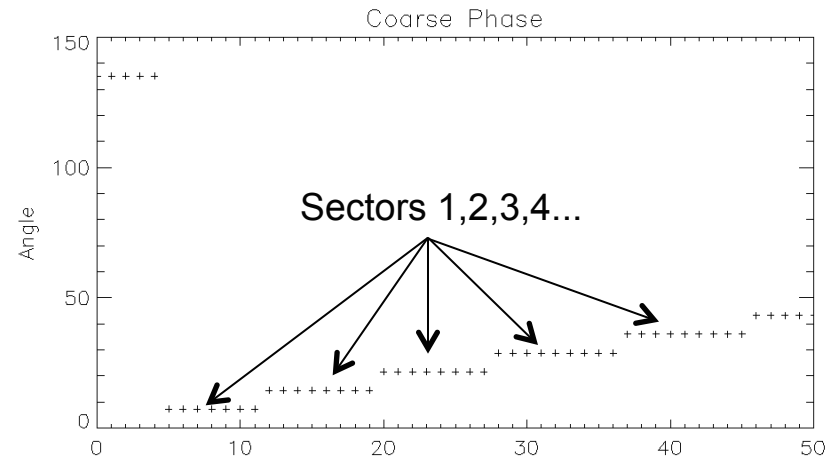
The patch to cycle despin torque by switching direction (I_q) every 16 packets and I_d between off and maximum every 4 packets.

The Control System Position Testing

A coarse phase sweep gives the most significant bits in the control system mirror position.
Sweeping at 7.2° intervals gives the finds the smallest position error for sector 4 and gives a new position of 29.66° .

Michael Tombs' model shows that sector 4 should produce a much greater torque in the reverse direction than we have exerted before.

Pitch Counter n (x 7.2)	Apparent Control System Pos.	Last known Motor Position	Effective field angle error	Max Torque T Id = 0	Iq = -1 Id = 0.5	Iq = +1 Id = 0.5
2	15.3	15.3	0.0	100%	-100%	100%
4	29.7	15.3	158.4	-93%	75%	-111%
5	36.9	15.3	237.6	-54%	96%	-11%
28	202.5	15.3	259.2	-19%	68%	30%



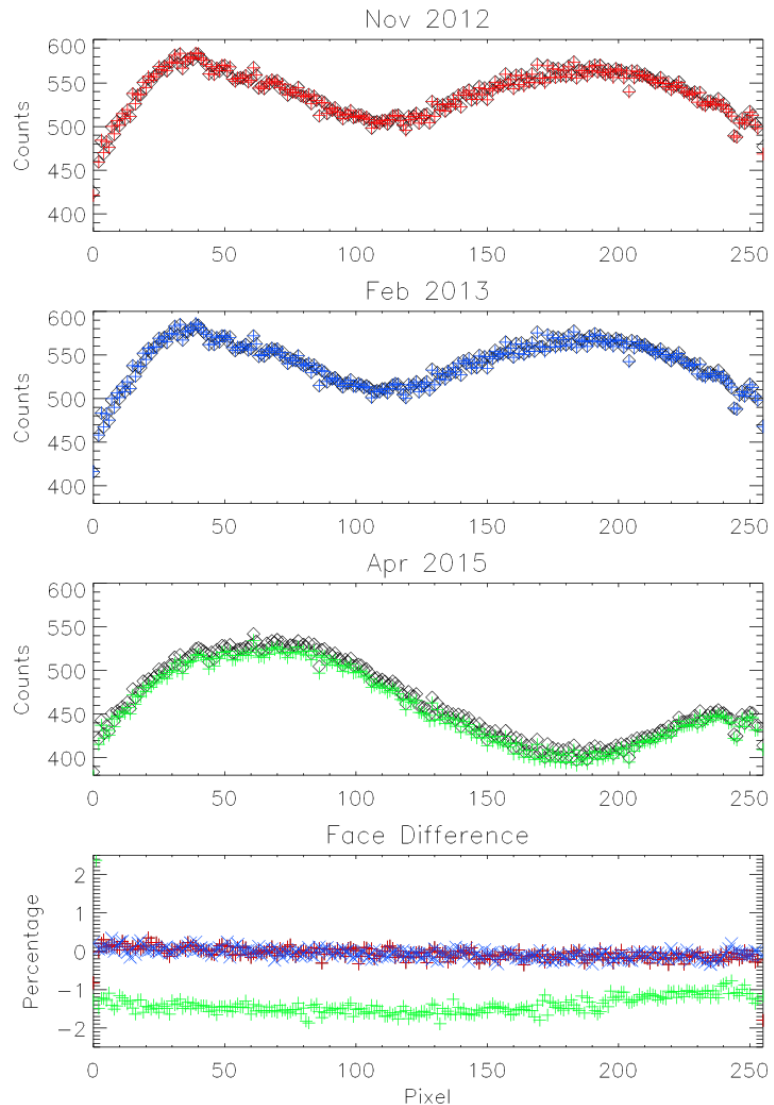
GERB-3 Mirror Face Comparison

The CALMON scans produce 750 illuminated GERB columns across a slowly varying source at 0.7 arcmin and ~ 0.6 s separation.

Comparing the mean pixel response for each mirror side we see that the ratio is stable in early operations but there is a small offset after the jam period.

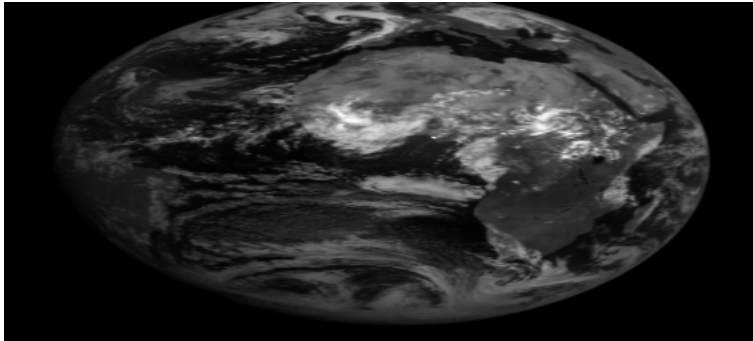
The mirror face responses to the CALMON signal have changed by $1.4 \pm 0.2\%$ over the two years relative to each other.

For GERB-4 IOS the DSM park angle has been updated to 67°

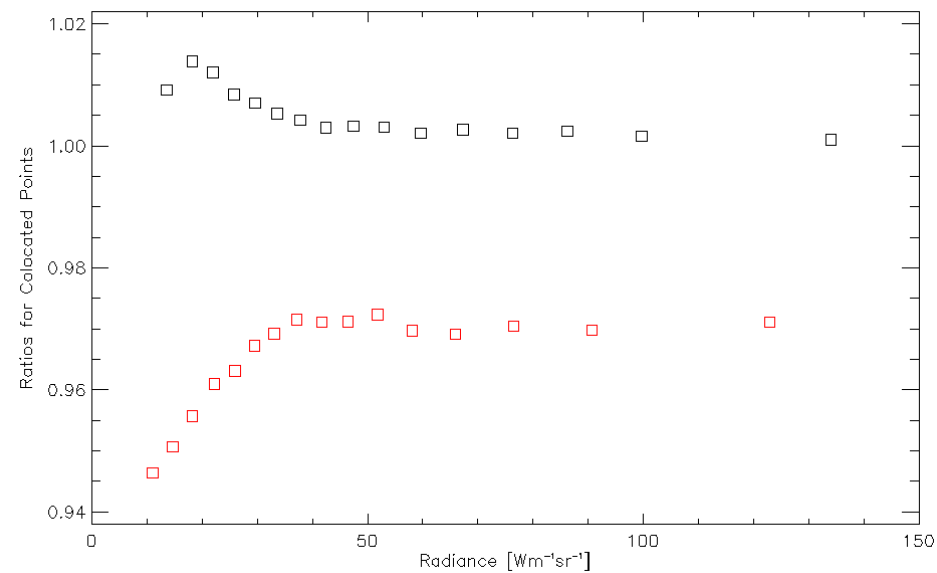
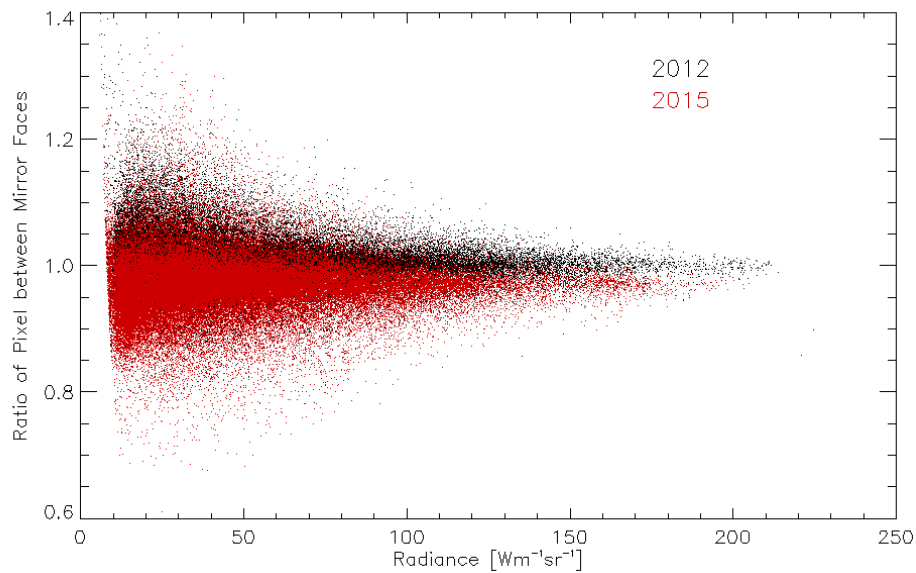
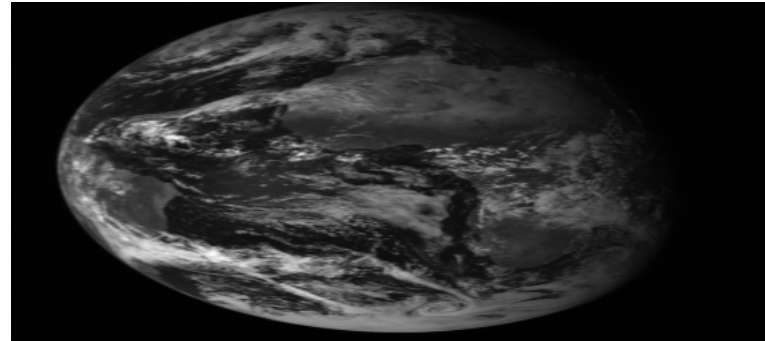


GERB-3 Earthview Mirror Face Comparison

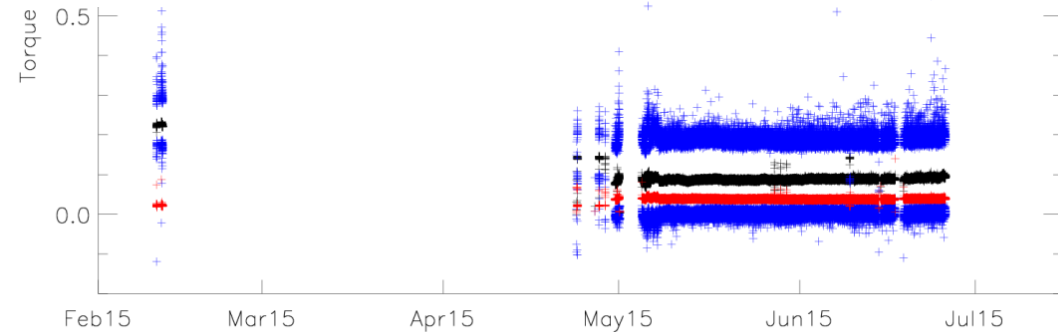
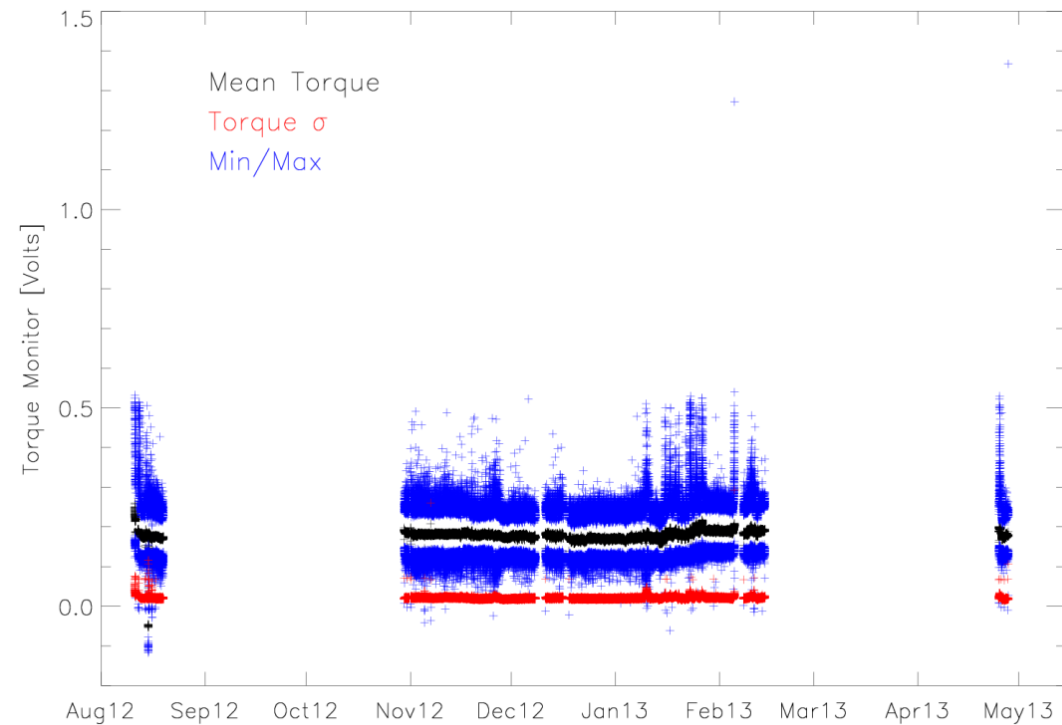
August 2012



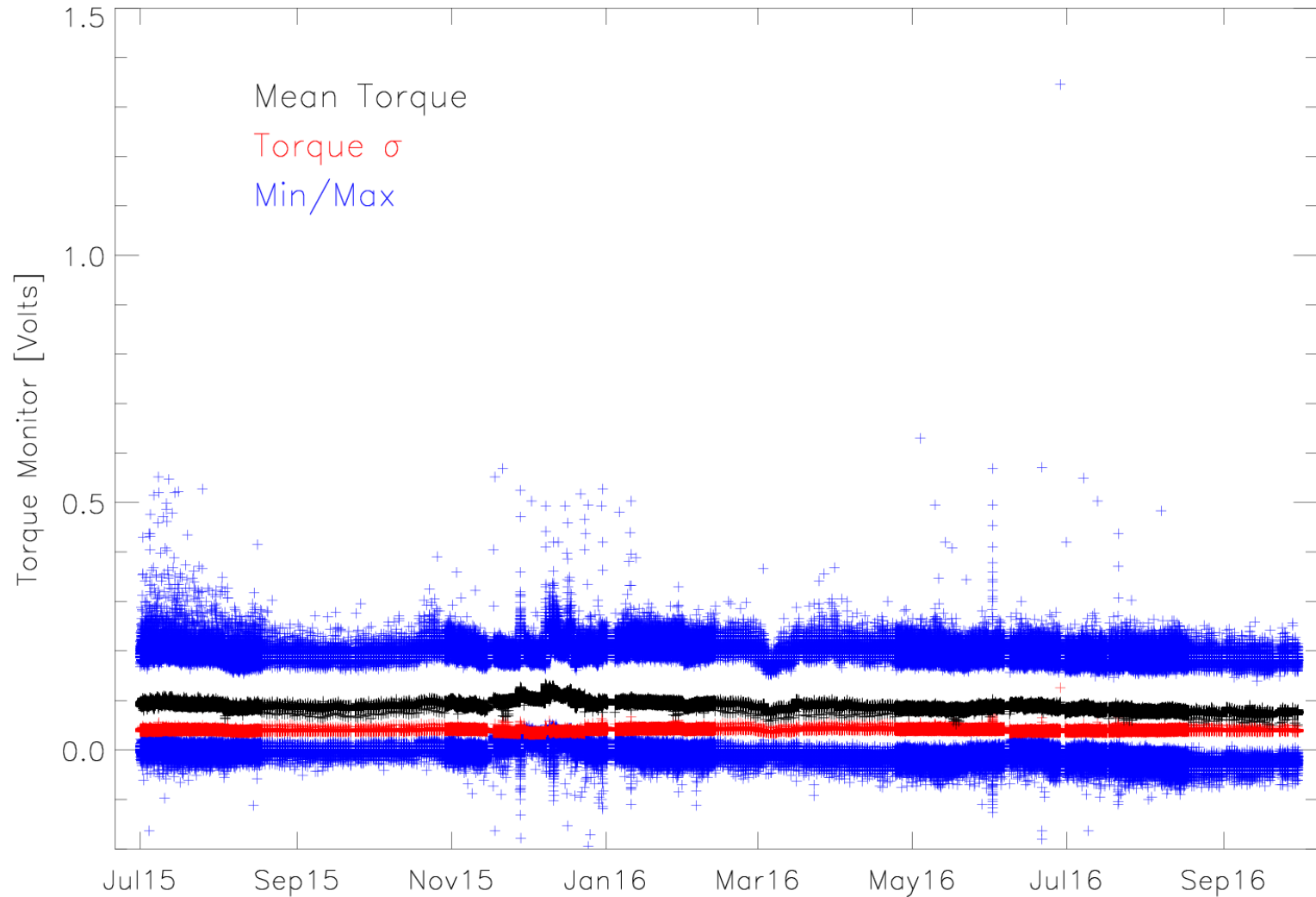
November 2015



GERB-3 Drive Torque Pre/Post Jamming Event



GERB-3 Torque Monitor



GERB-3 Mirror Incidents since Restart

On GERB-3 AutoSUNBLOCK (Patch 302) and AutoDisable (Patch 310) are always active allowing the DSM to respond quickly to events and avoid driving with maximum torque for long periods. Patch 302 also gives a burst of high resolution mirror telemetry up to the point the limits are violated.

There have been thirteen mirror mispointing events since the restart.

1st May 2015

15th June

17th June

1st July

20th November

28th November

23rd December

26th December

30th December

28th May 2016

28th June

16th July

20th July

Both patches tripped

Just Patch 302

Both patches tripped, failed routine start up

Just Patch 302

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Just Patch 302

Just Patch 302

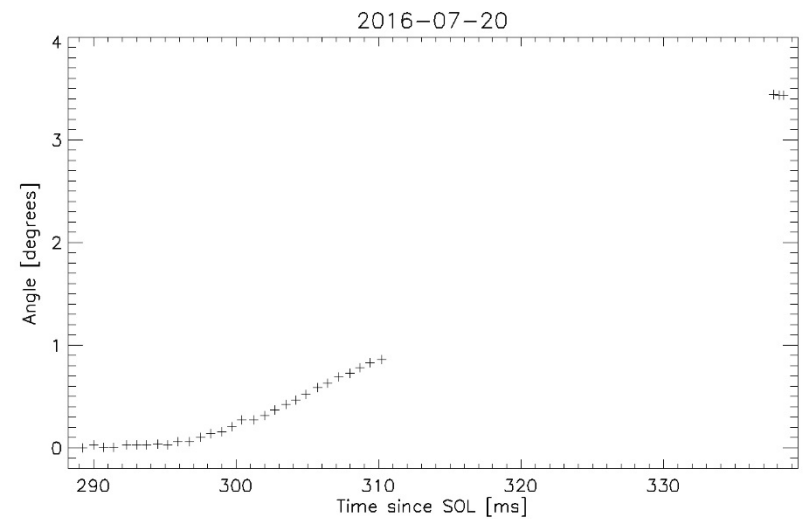
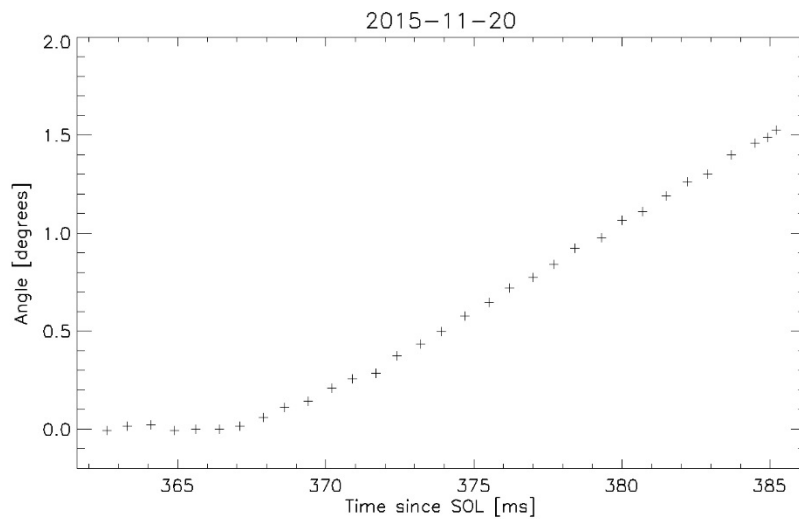
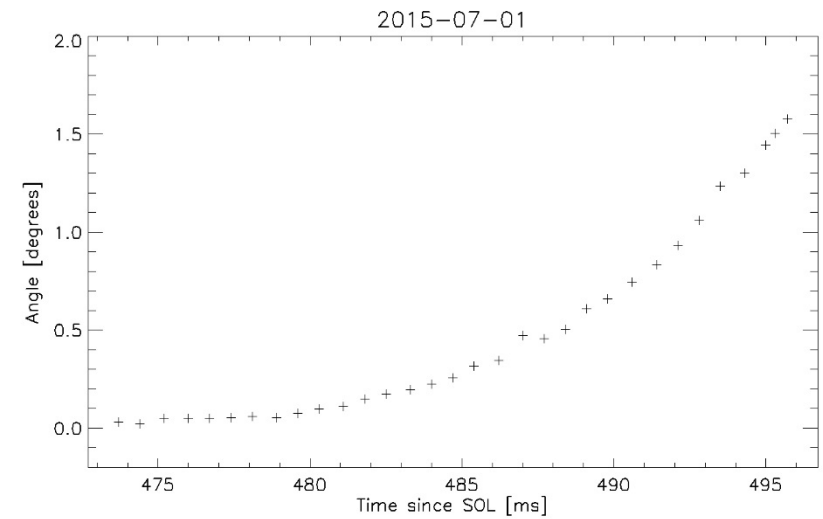
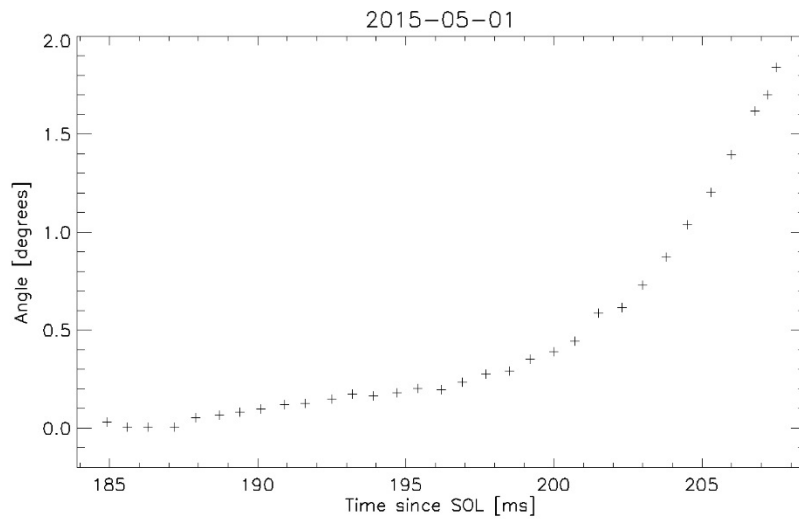
Just Patch 302

Both patches tripped, failed routine start up

Just Patch 302

Just Patch 302

GERB-3 Patch 302 Telemetry from DSM Incidents



Restart – 17th June 2015

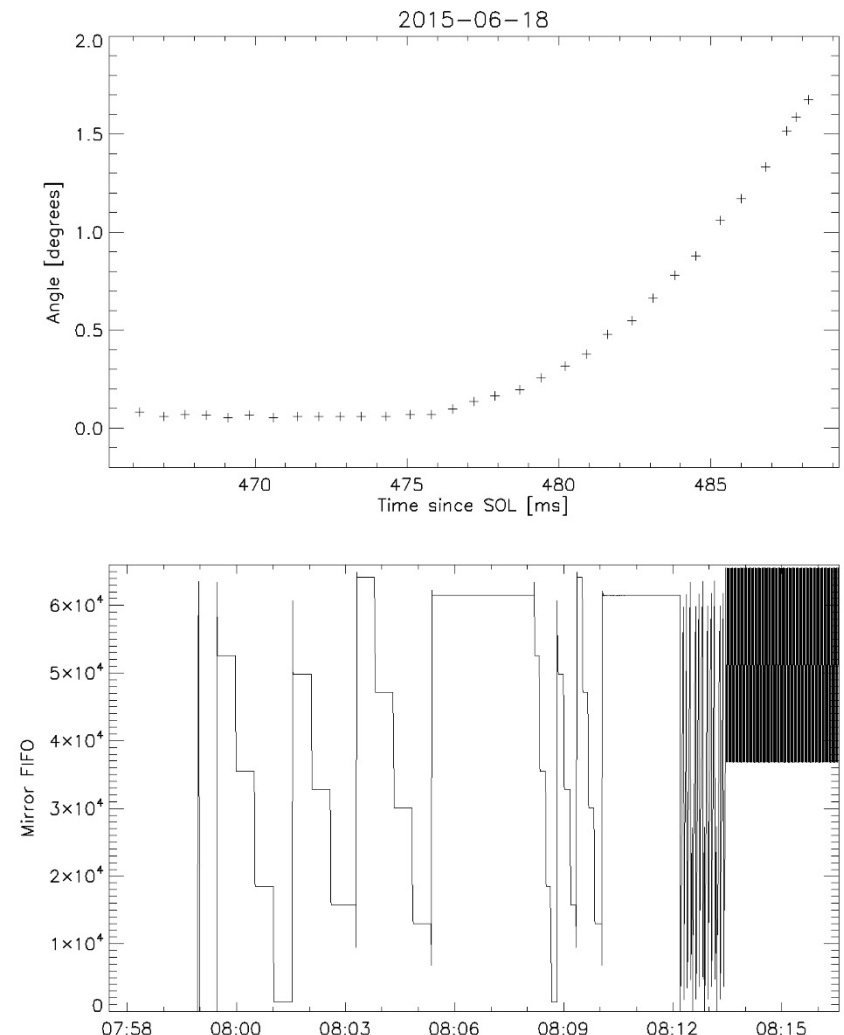
GERB-3 DSM returns to home position (0°) on re-enabling the drive.

DSM fails to achieve lock when commanded to SUNBLOCK (rotation without scanning)

Commanding SAFE the drive returns to the home position.

Using position commanding unavailable in previous instruments the DSM was driven backwards for two rotations in 30° steps.

After two nominal backwards rotations lock was acquired in SUNBLOCK and nominal imaging was resumed.



Restart – 28th June 2016

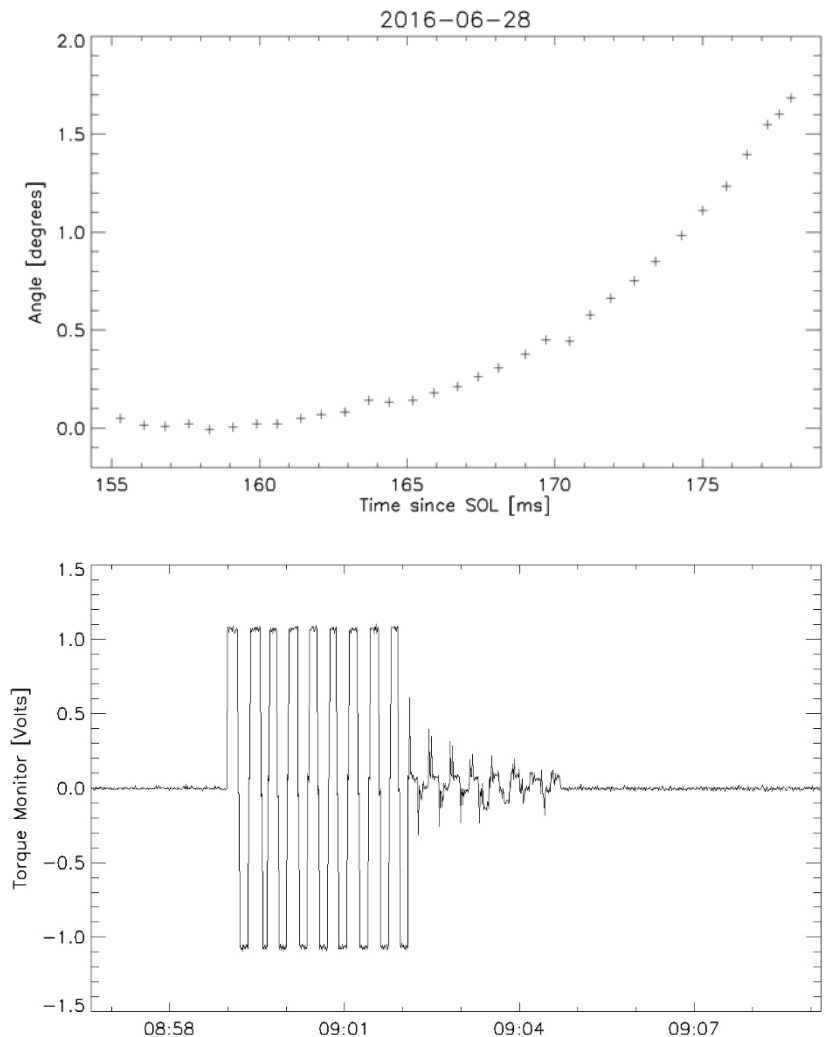
After tripping both patches the drive stops at $\sim 277^\circ$.

Restart attempted by backing off to 270° and commanding SUNBLOCK. Lock is not regained.

Another attempt to command the drive in the reverse rotations in 30° steps fails when the drive stops at 222° on commanding to 210° .

Commanding back and forth between 180° and 330° succeeds in freeing the drive. Nominal imaging is resumed.

Combining the two patches has thus far avoided long periods exerting maximum torque and protected against another jam.



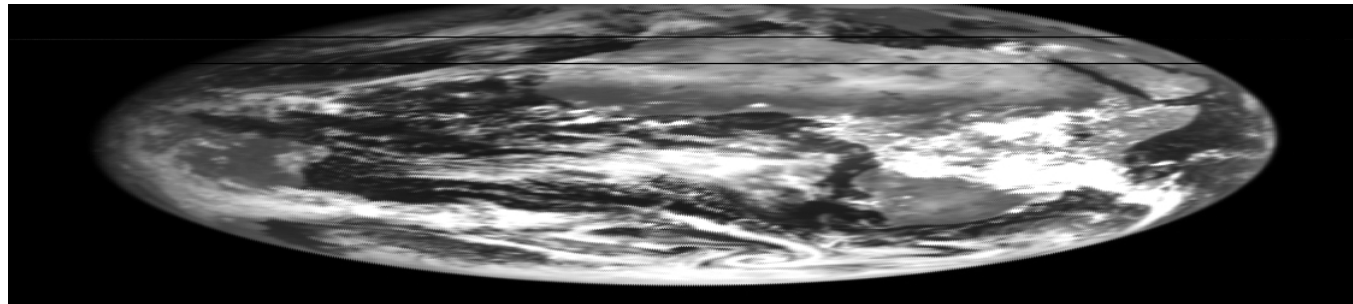
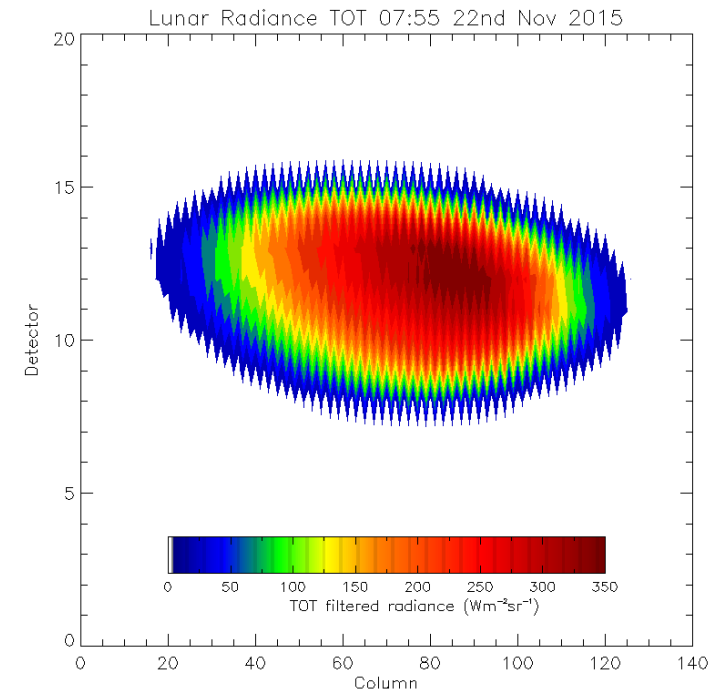
GERB-4 Commissioning Pre First IOS Storage

GERB-4 functional commissioning was completed on the 4th Nov 2015. The report was approved by the TRB.

Some of the calibration commissioning activities were completed:

- Lunar scans (21st-23rd Nov 2015)
- CALMON scans (9th Nov)
- Mirror Offset test (4th Nov)
- PSF limb scans (3rd Nov)
- Cross calibration (4th Nov – 6th Dec)

GERB-4 was switched off for the first IOS period on the 6th of December.



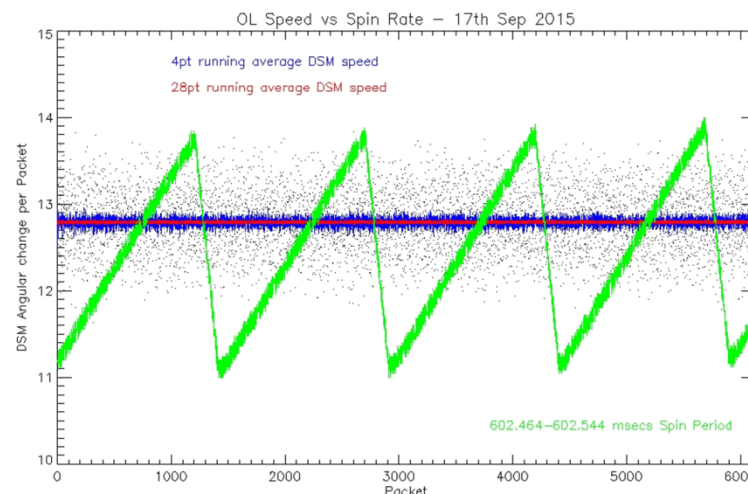
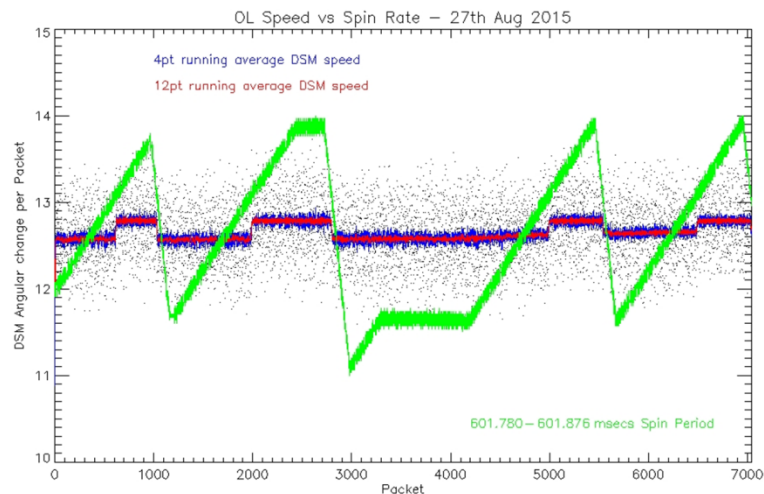
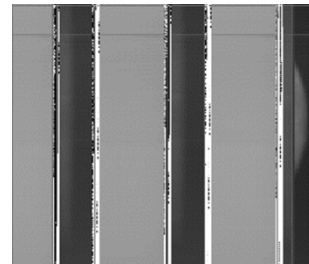
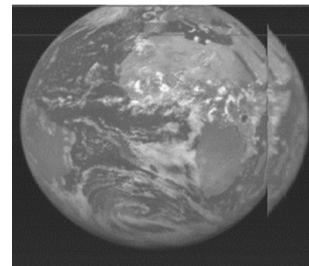
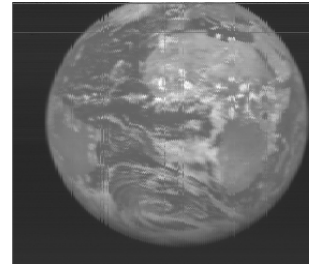
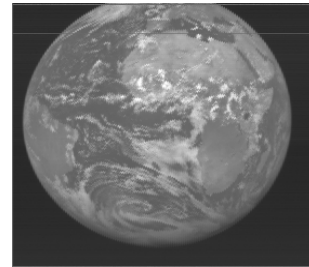
GERB-4 Early Commissioning and Spin Rate Anomaly

The GERB-4 Commissioning began on 6th August and during the early testing proceeded nominally.

Losses of lock in SUNBLOCK were attributed to rough running of the bearing but the defects in the initial images whilst the mirror was reporting lock contradicted this.

Functional commissioning was suspended to test the anomaly.

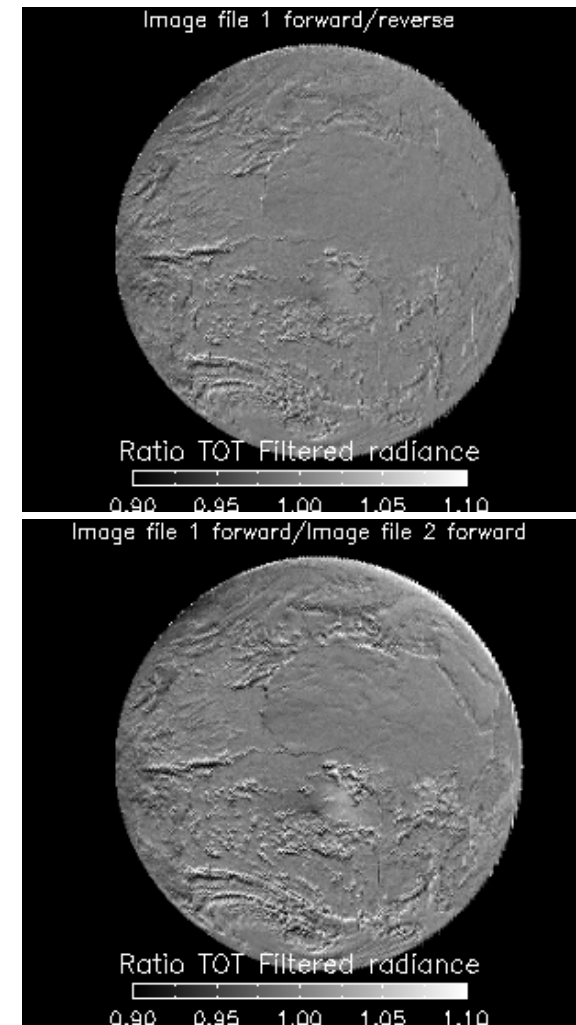
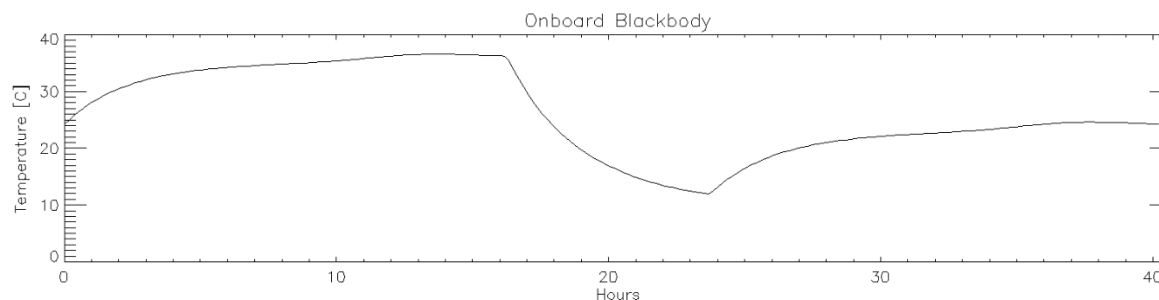
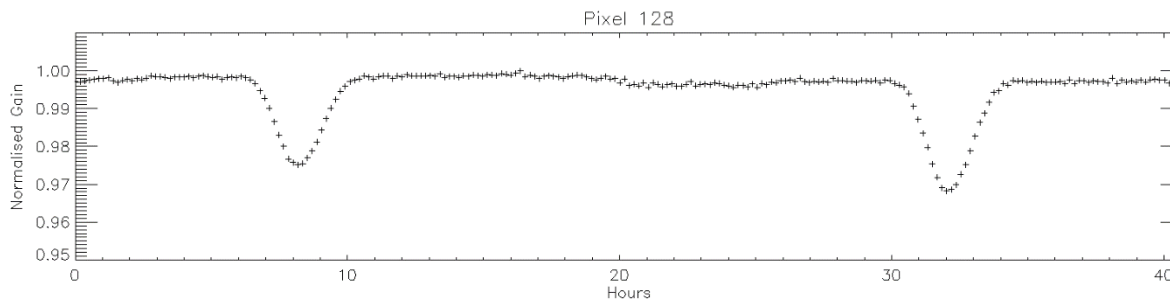
Satellite spin rate was identified as the critical factor. Spin rate higher than 99.691 rpm have consistently triggered the problem.



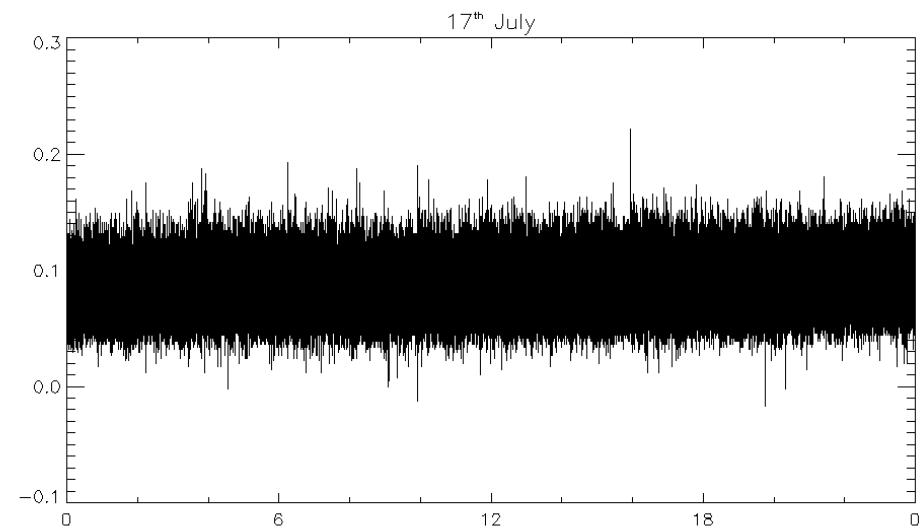
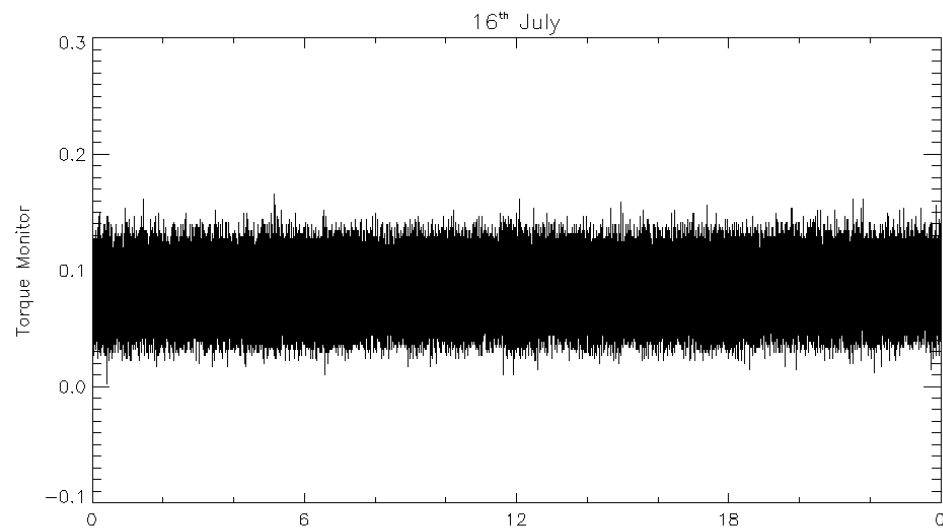
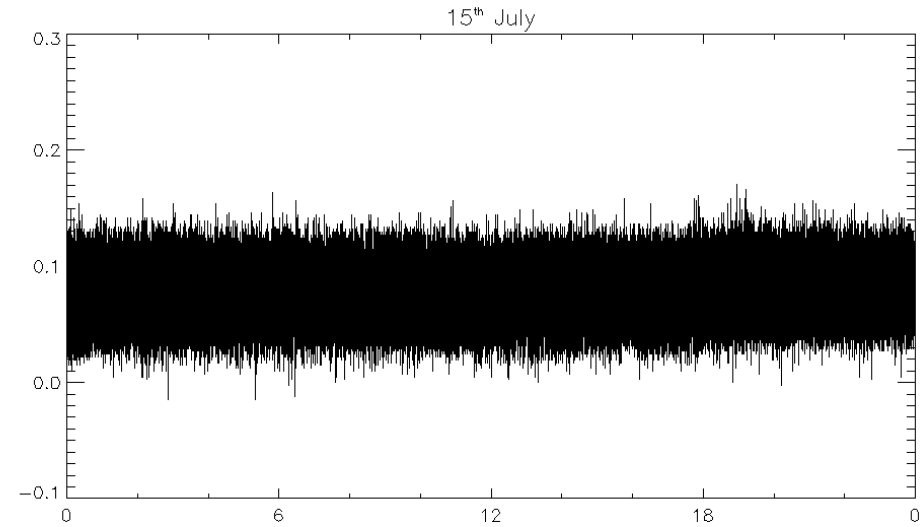
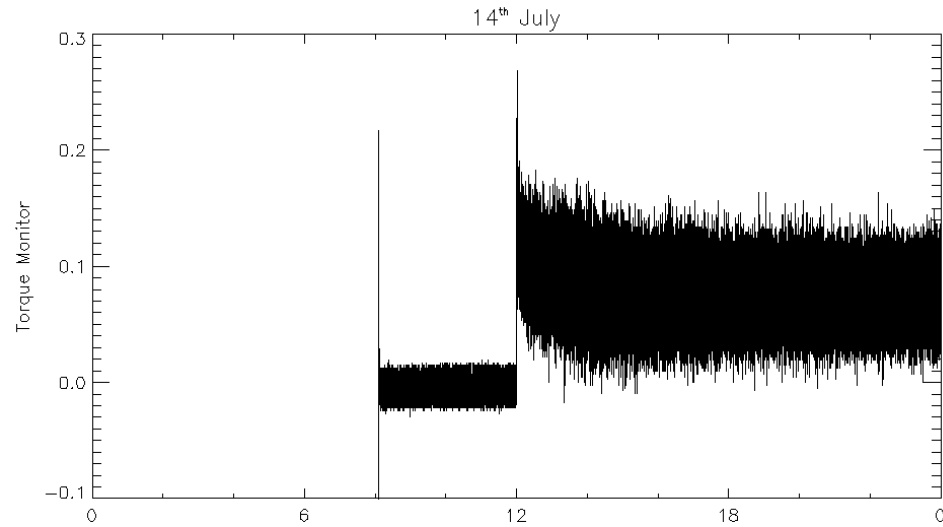
GERB-4 Commissioning During First Activation

All calibration commissioning activities have been completed as of the end of the first IOS activation:

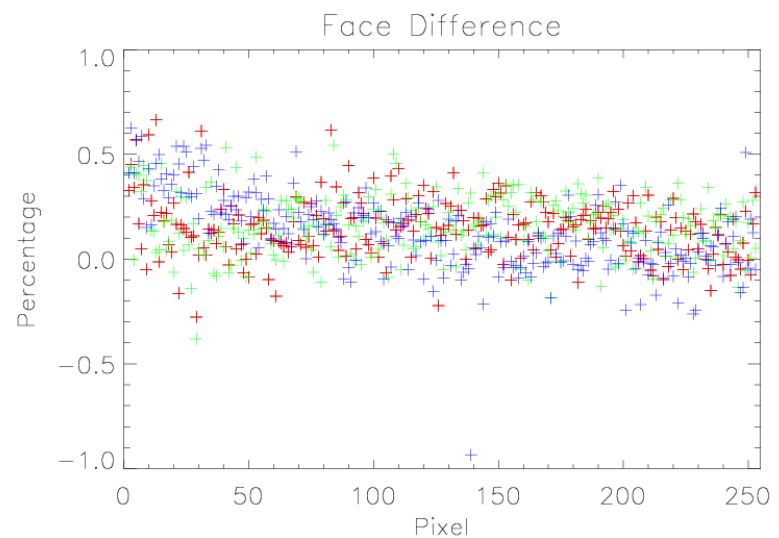
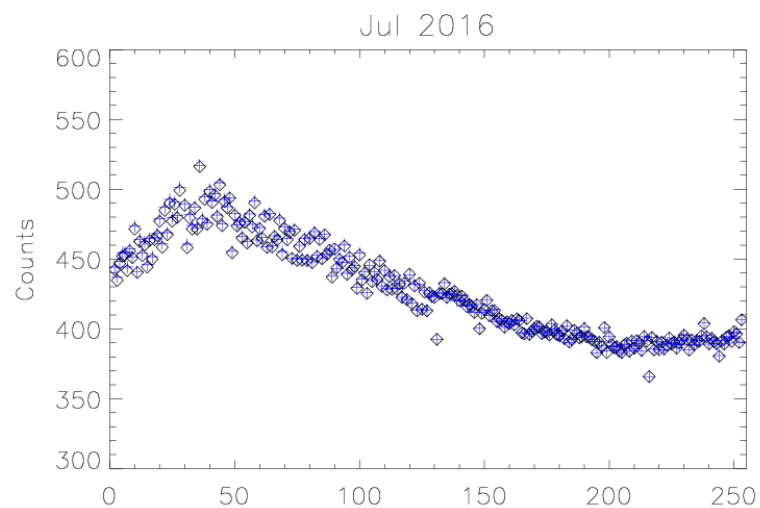
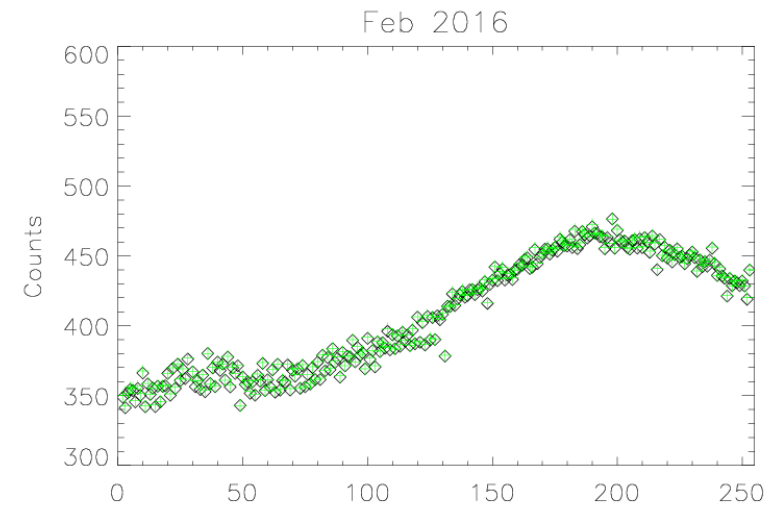
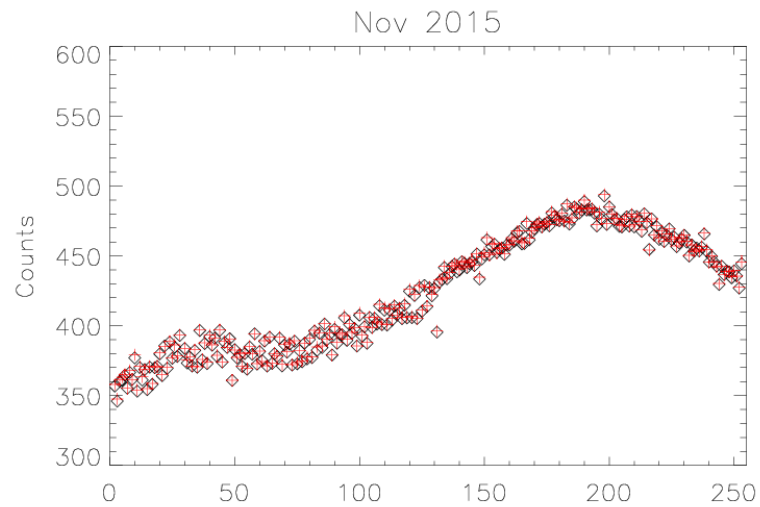
- Deep Space scans (2nd-4th Feb 2016)
- Scan direction dependency (4th Feb)
- Nominal PSF scans (9th Feb)
- African coastline PSF scans (10th Feb)
- CALMON scans (10th Feb)



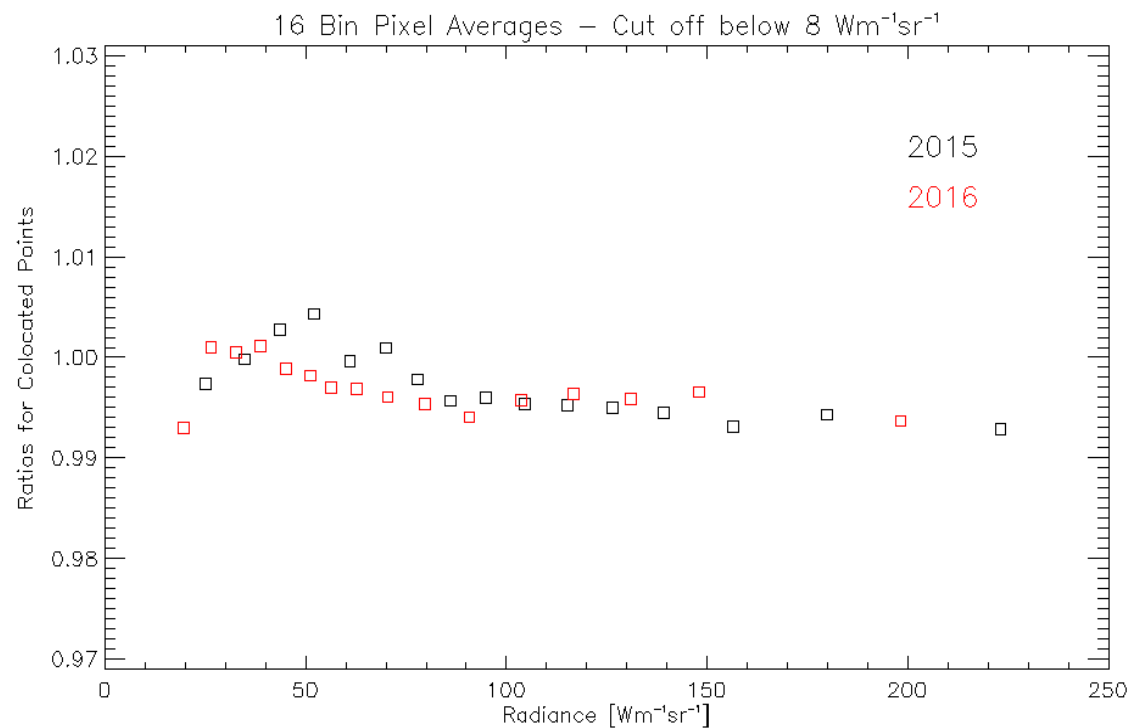
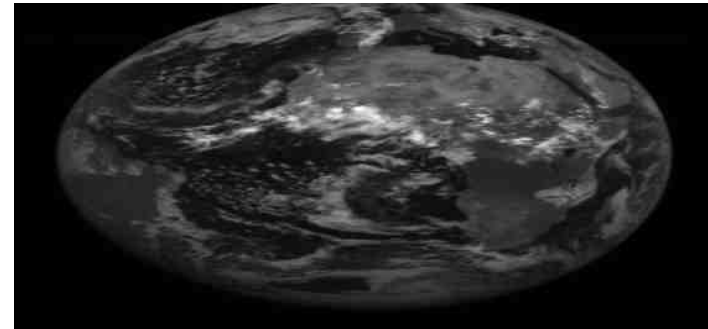
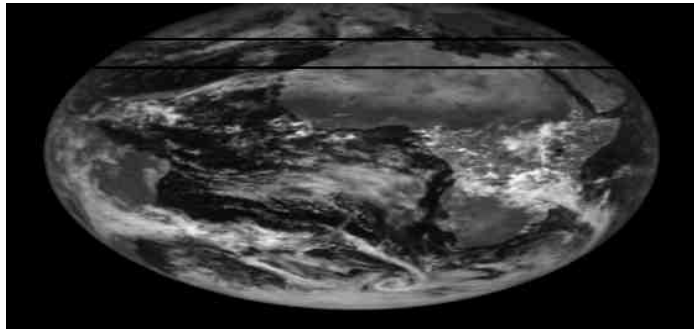
GERB-4 First Routine Activation – DSM Torque Monitor



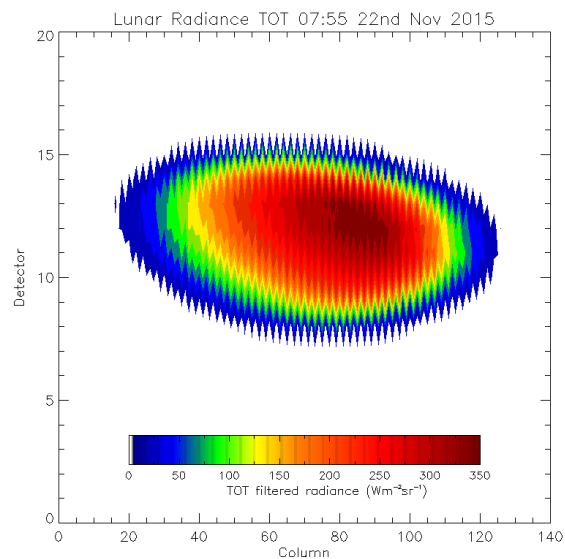
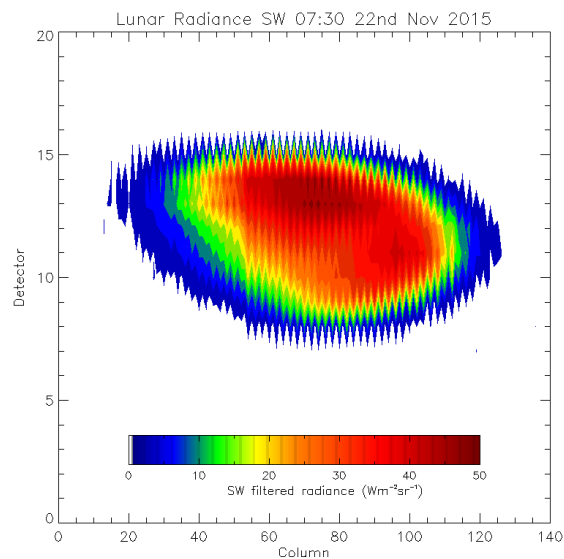
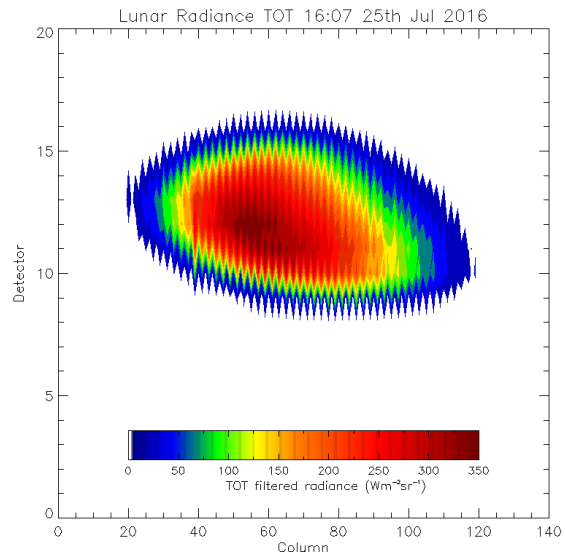
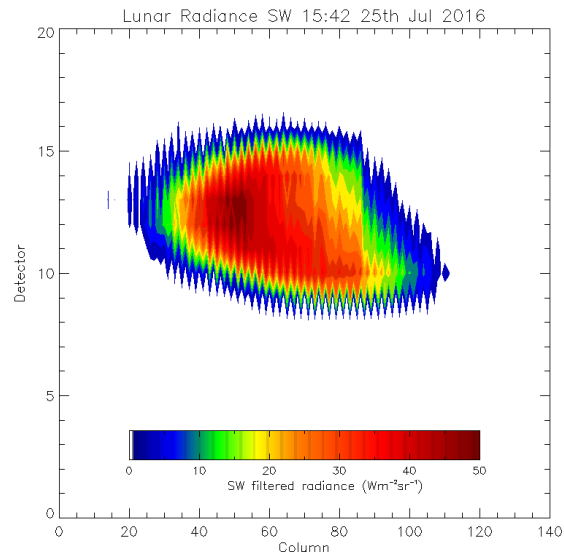
GERB-4 Activation - CALMON Mirror Face Performance



GERB-4 Activation - Earthview Mirror Face Performance



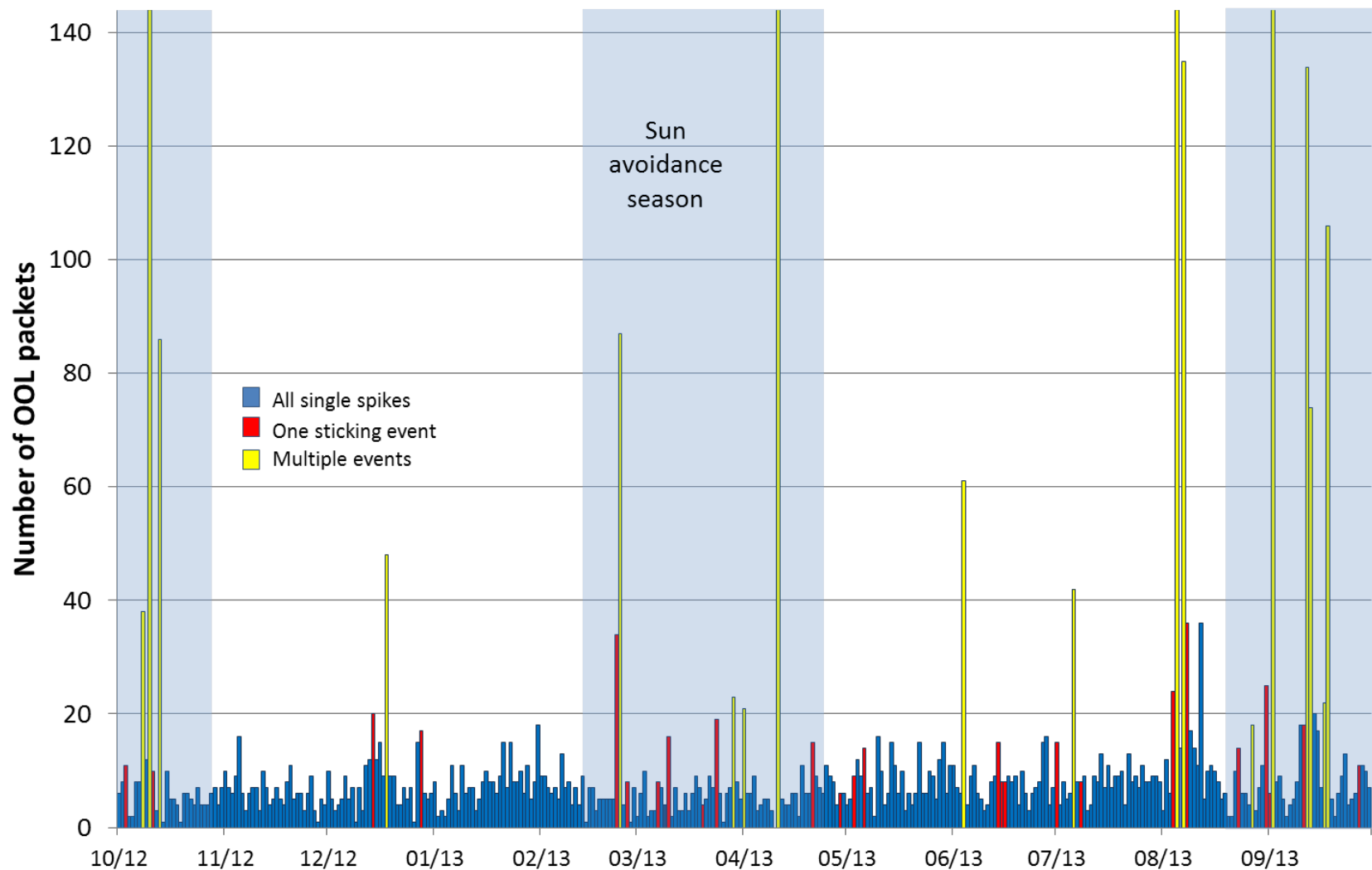
GERB-4 Activation – Lunar Scans



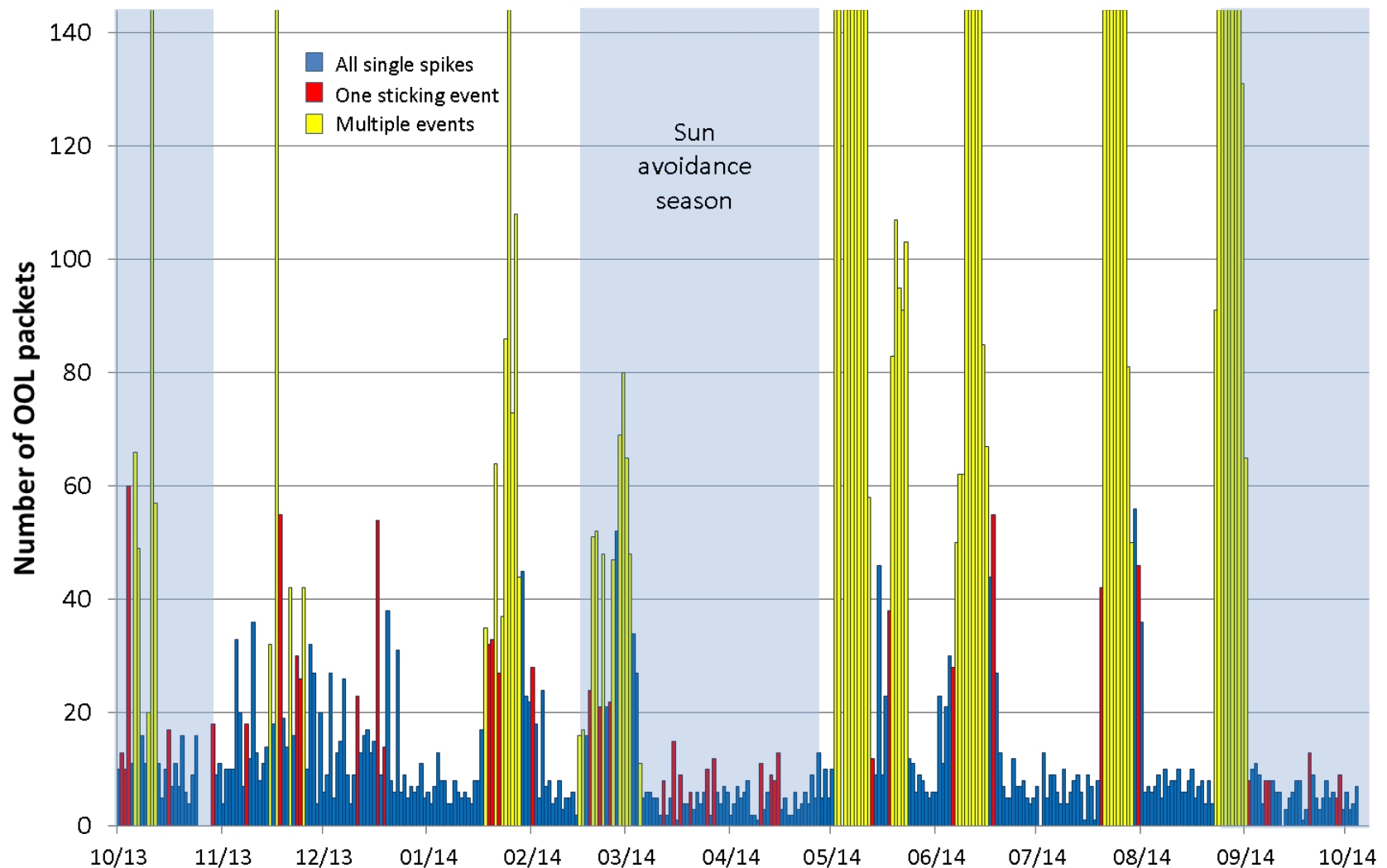
GERB-4 First Routine Activation

- The GERB-4 drive bearing has shown no change in pointing performance and is still running well within specification.
- The new park position has not led to any relative change between the optical performance of the two faces
- As yet it is too early to tell whether the new park position will protect the GERB-4 despin from ageing effects as these only began to appear after 6 to 12 months on previous instruments.
- Lunar data was acquired for this GERB-4 period and should be for future activations if an observation opportunity arises.

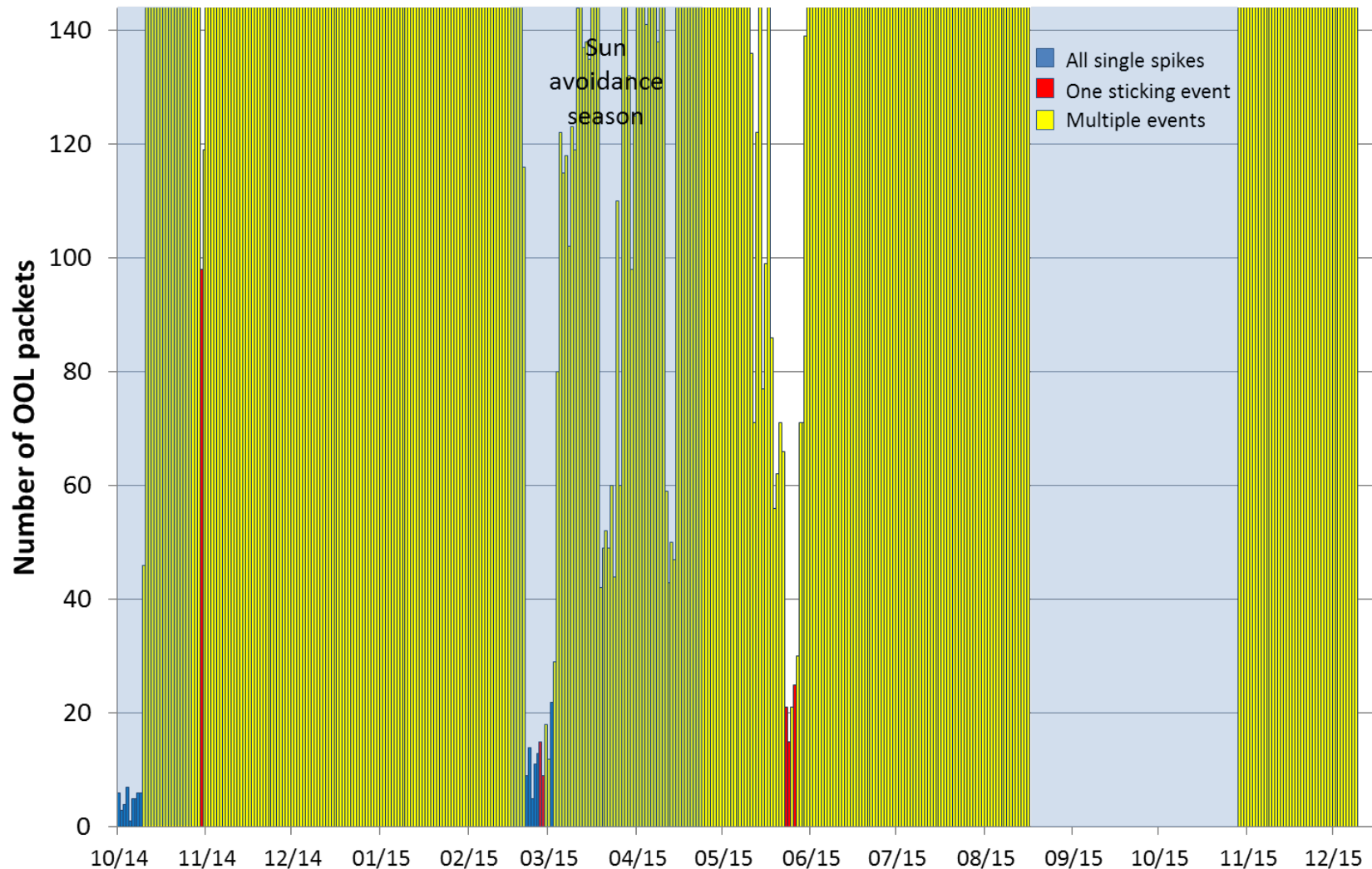
Daily GVMERR OOL on GERB-1 Despin Mirror, 2012-13



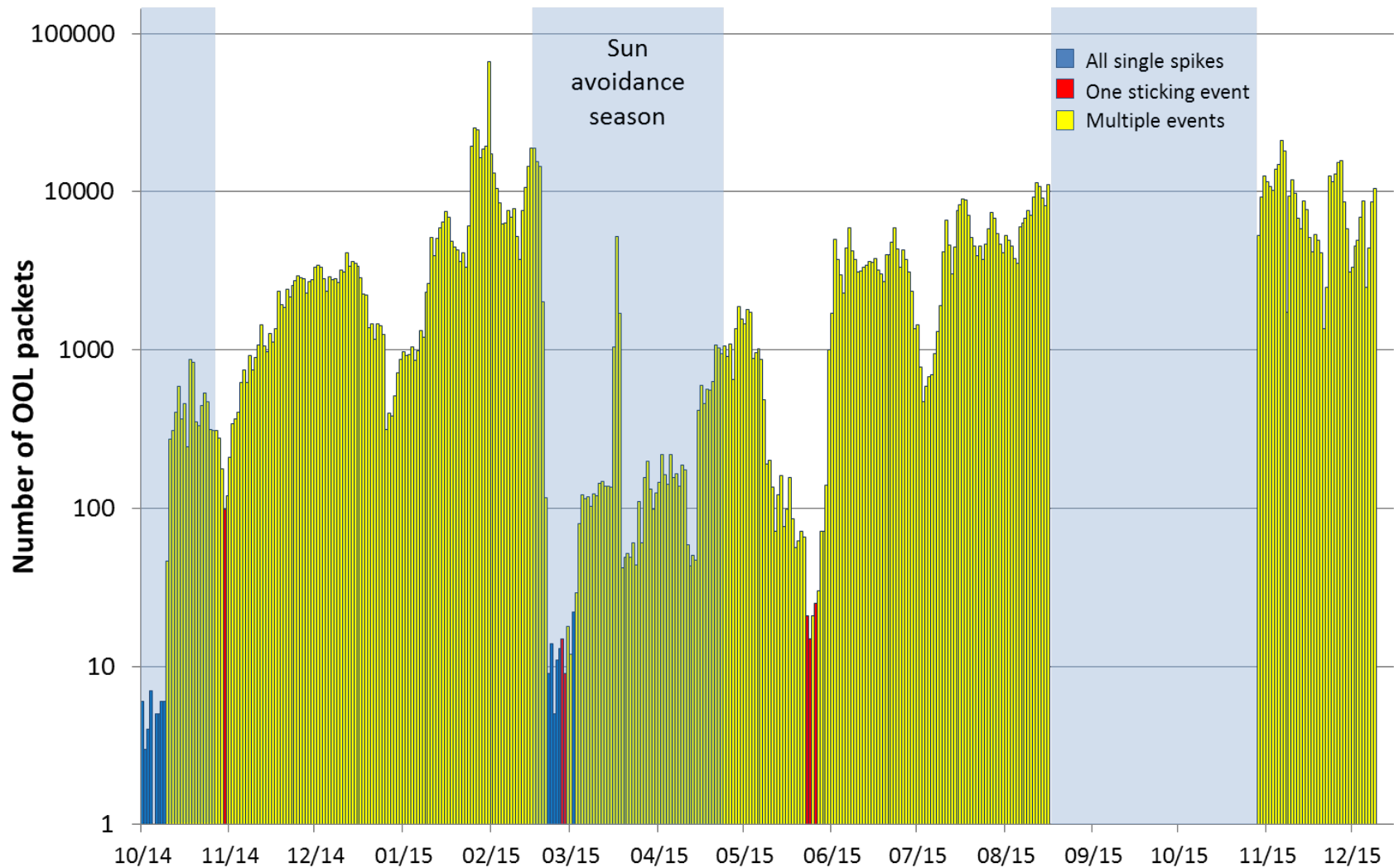
Daily GVMERR OOL on GERB-1 Despin Mirror, 2013-14



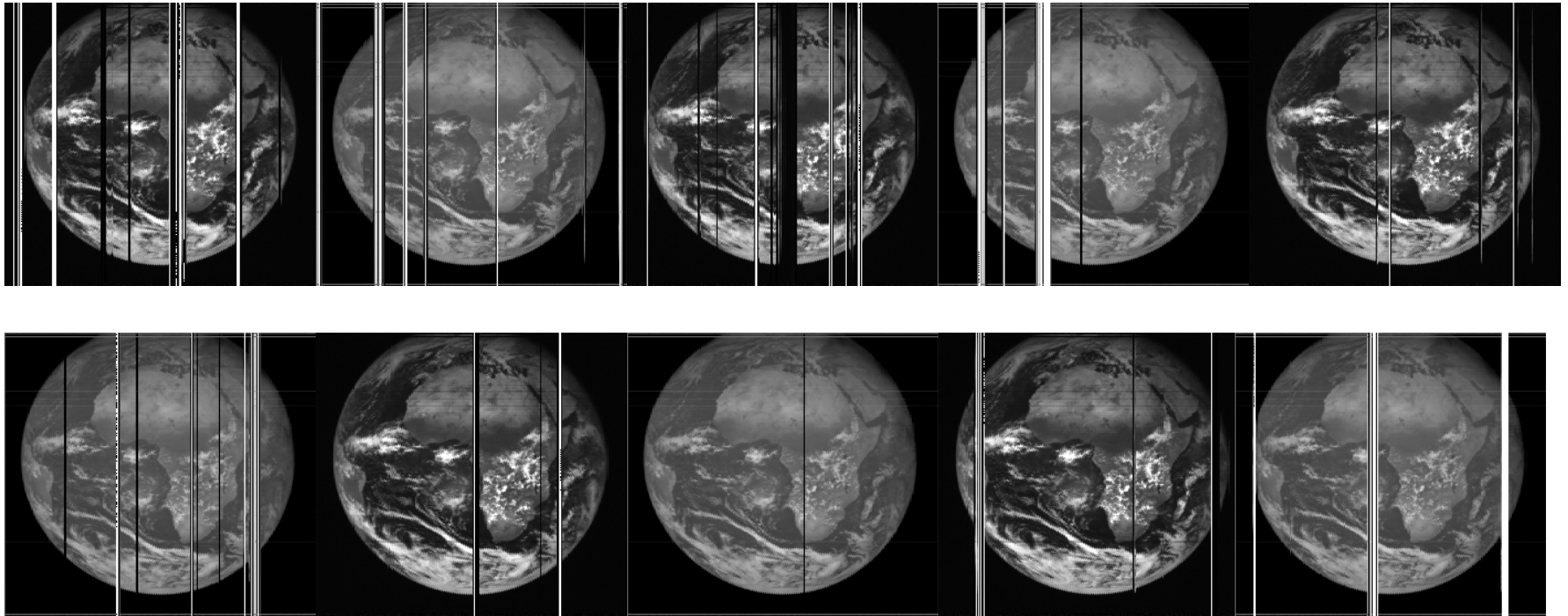
Daily GVMERR OOL on GERB-1 Despin Mirror, 2014-15



Daily GVMERR OOL on GERB-1 Despin Mirror, 2014-15

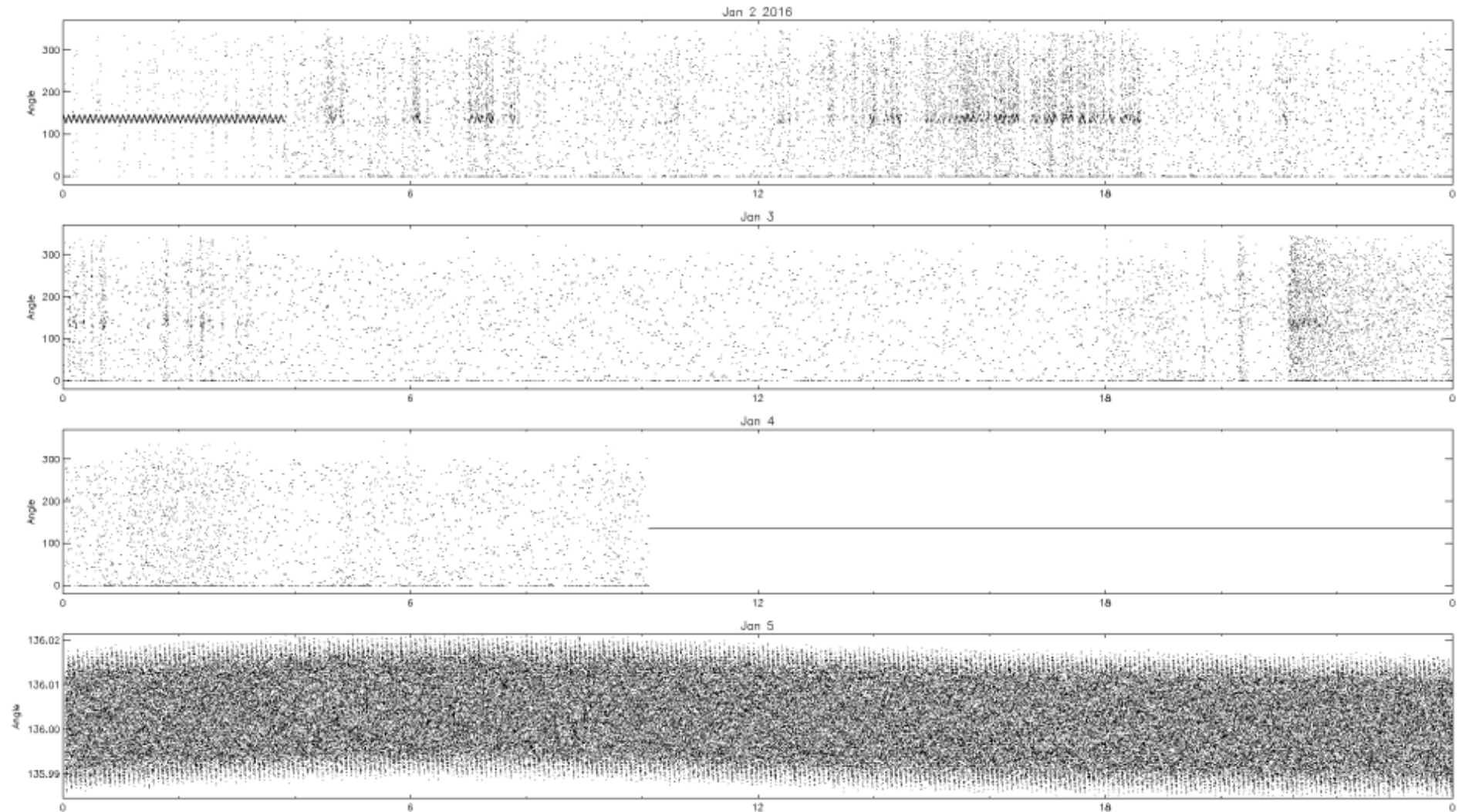


Impact on GERB-1 Images

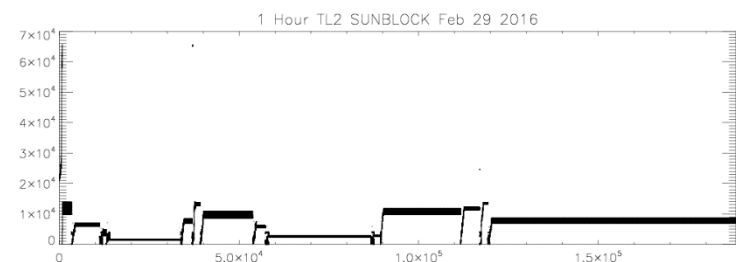
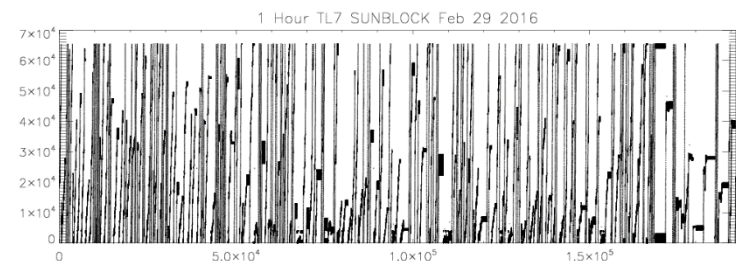
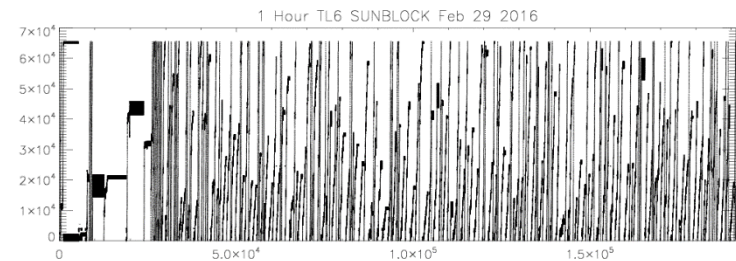
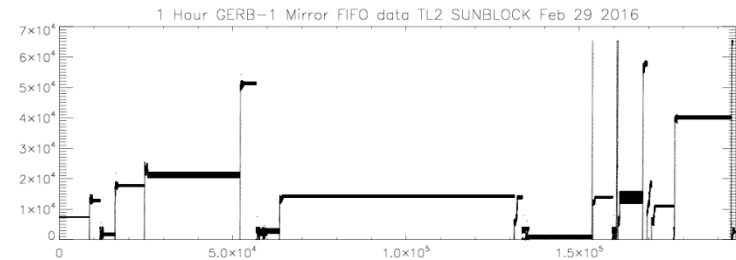
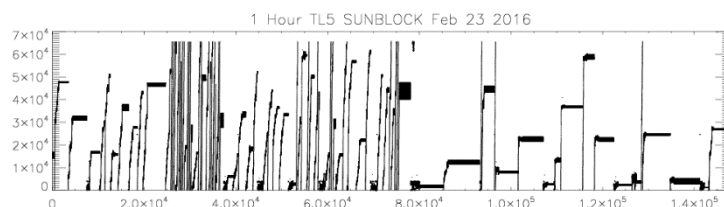
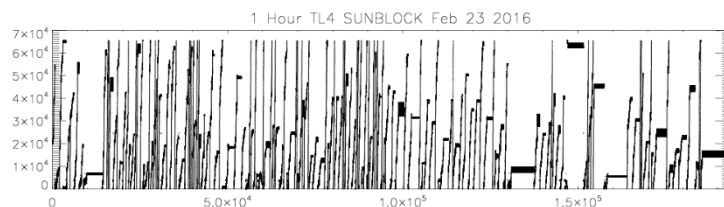
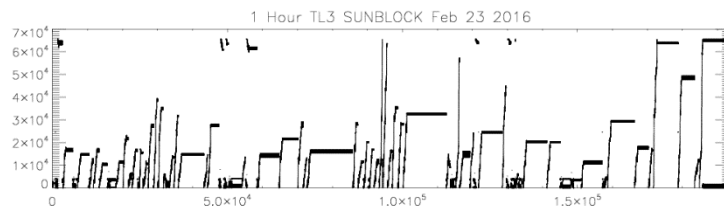
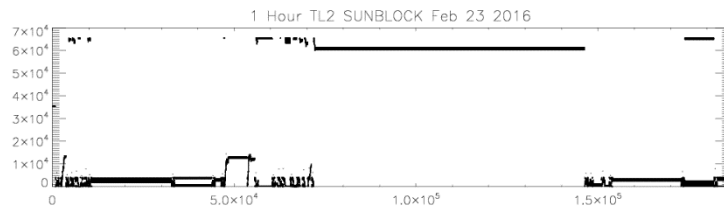
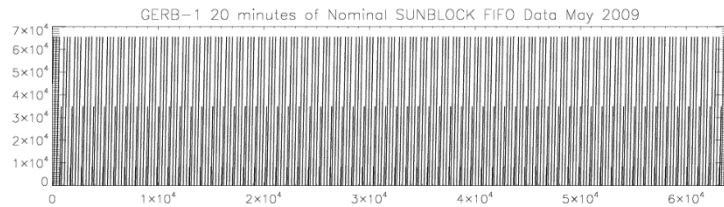


Consecutive images taken from ~12:00 UTC on the 10th of December

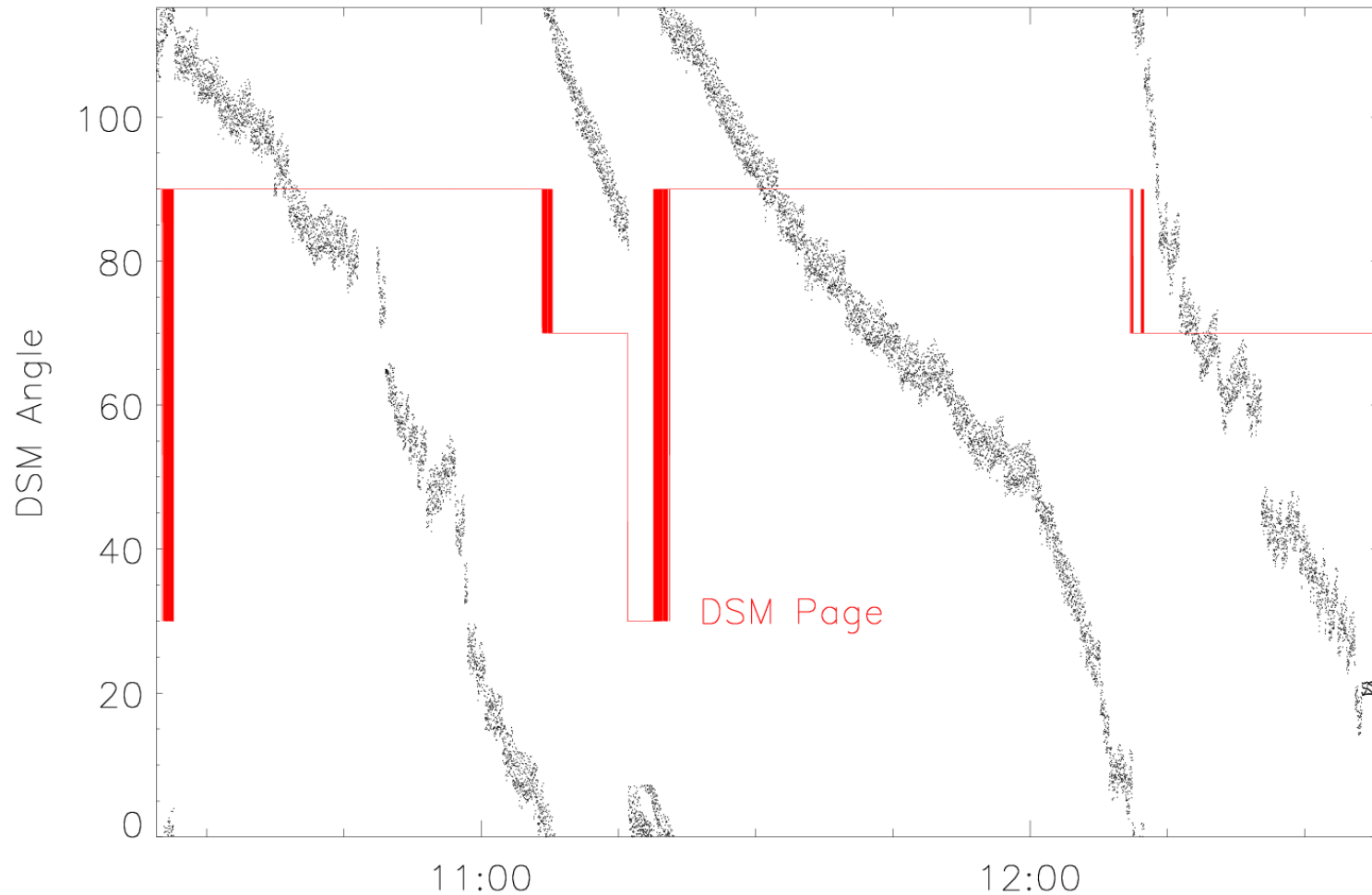
Severe GERB-1 Event : SOEP_E



Testing Since Major GERB-1 DSM Incident – Feb '16



Testing GERB-1 DSM – 0x2020 FIFO Mode – 16th Aug '16



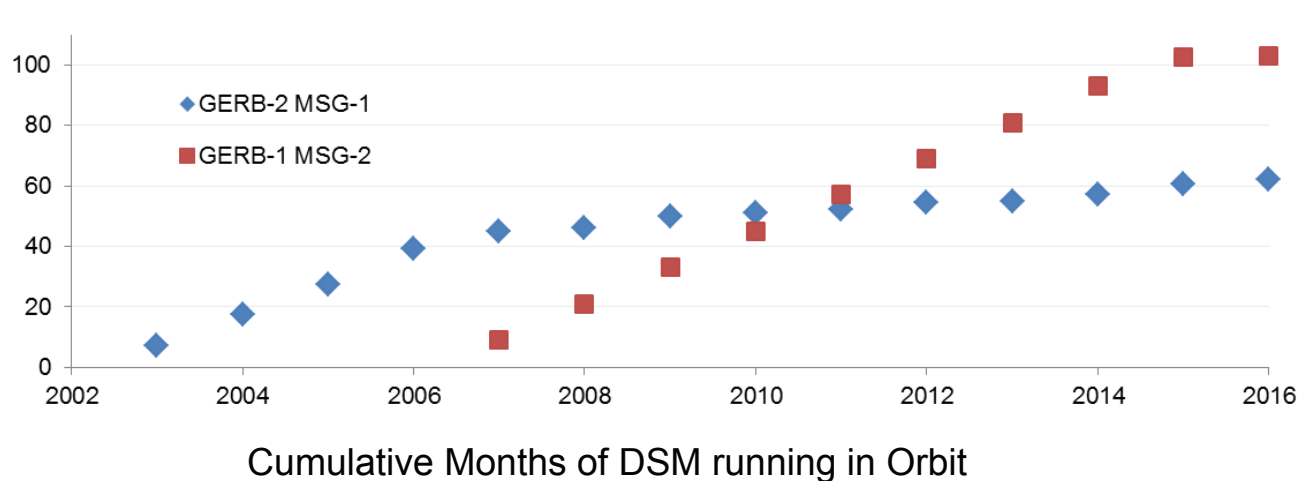
GERB-1 vs GERB-2 DSM Bearing Life

GERB-1 bearing running time exceeded that of GERB-2 during 2010.

This neglects running before launch which was also longer for GERB-1 and included an exceedance of the limit to running in air.

The performance of the bearings in orbit thus far show similar differences to the two lifetime tests. GERB-1 showing a more consistent decline while GERB-2 has recovered to low sticking levels currently.

On the ground one bearing was very rough by the end of testing and the other still performed well.



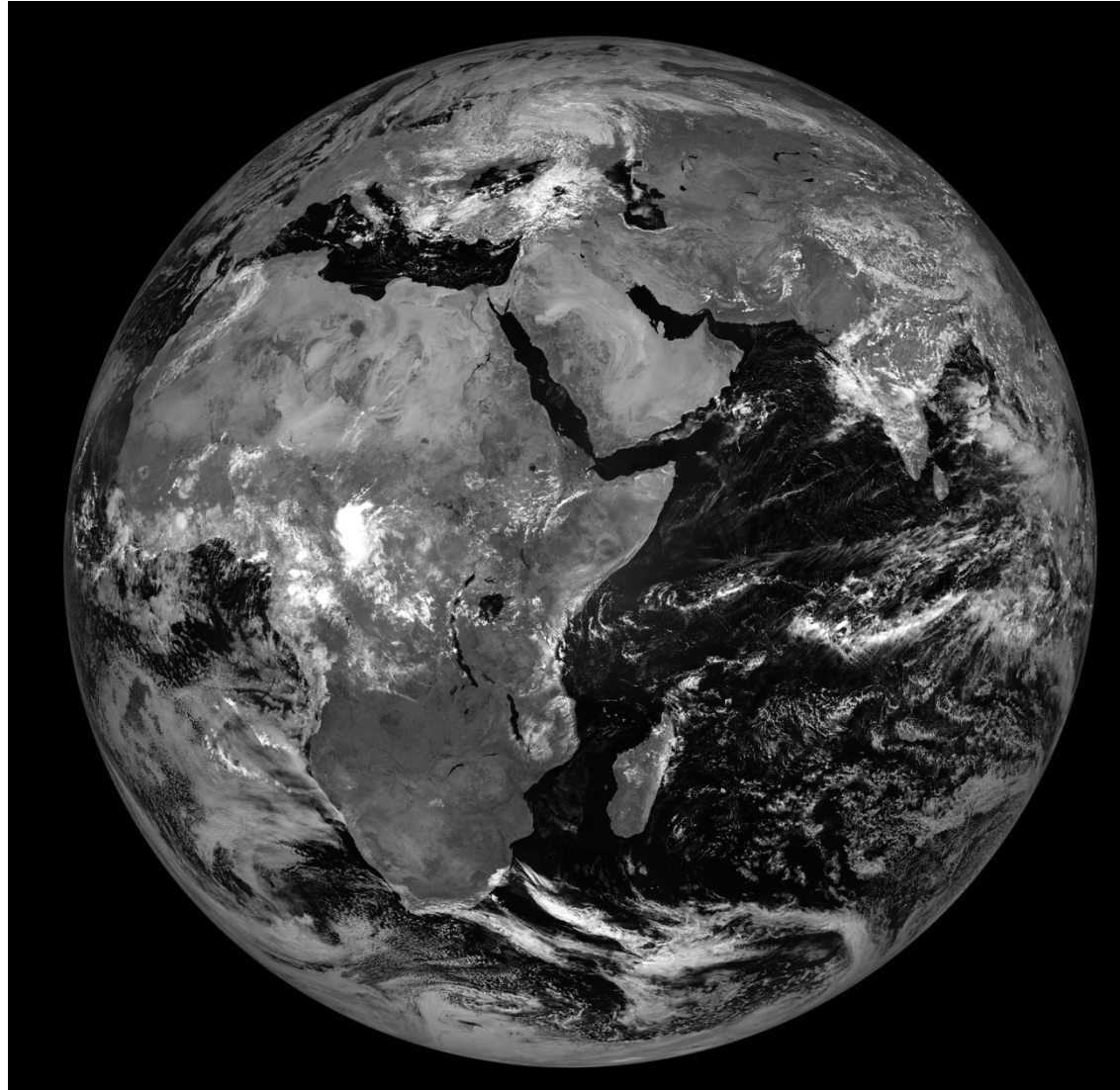
MSG-1 GERB-2 Move to 41.5°E

In early July MSG-1 began the approximately 11 week relocation from 3.5°E to 41.5°E

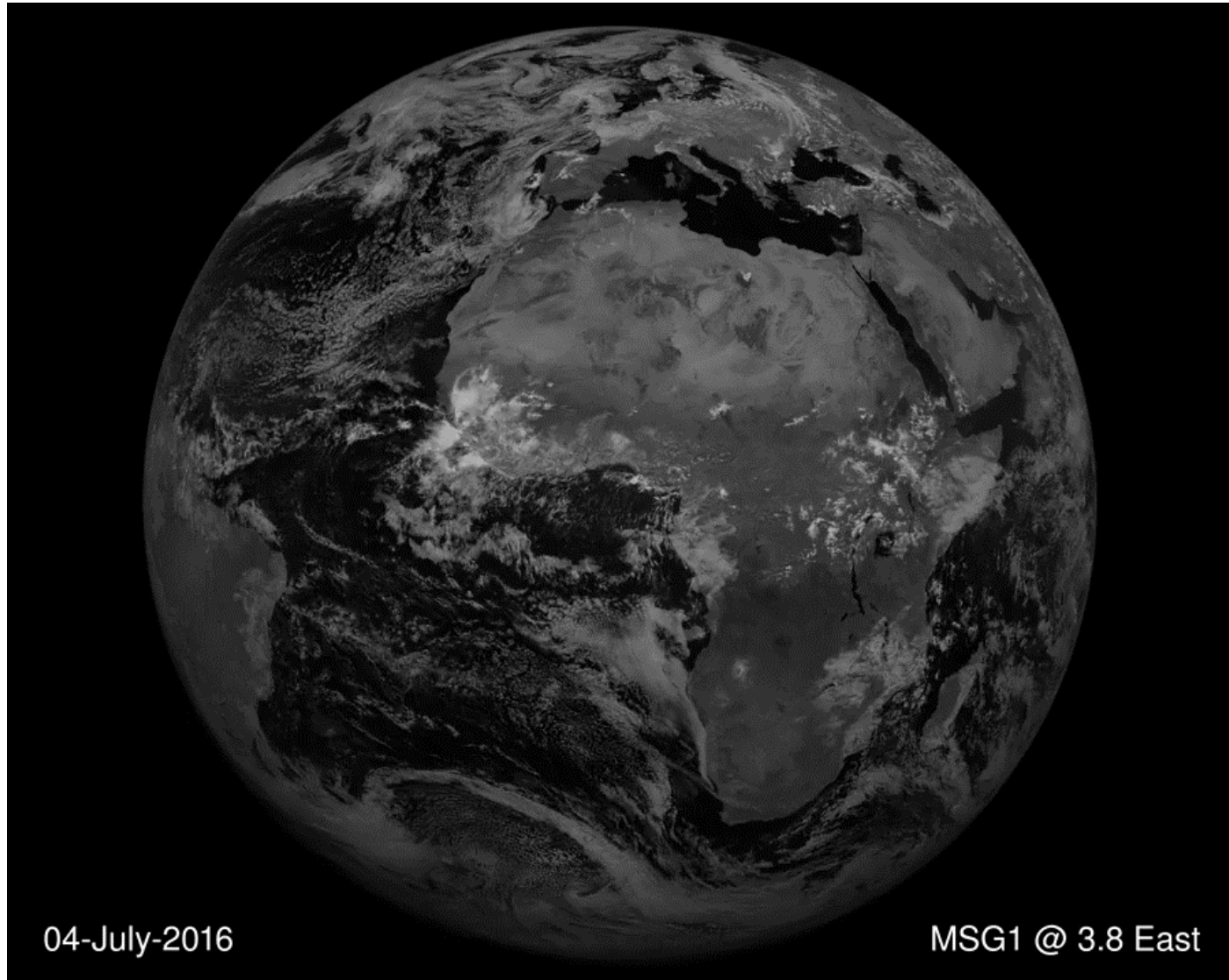
SEVIRI on MSG-1 was imaging throughout the transition.

Drift completed on September 21st with two manoeuvres 12 hours apart.

Two month parallel observations with Meteosat-7 planned as part of the validation before MSG-1 begins IODC operational service early in 2017.



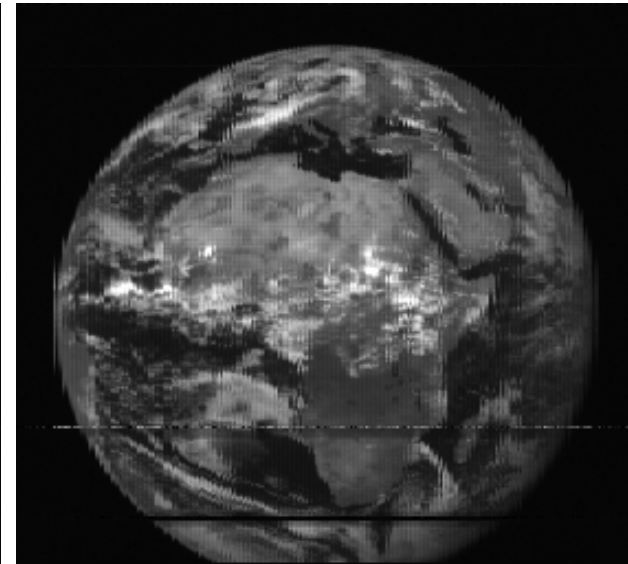
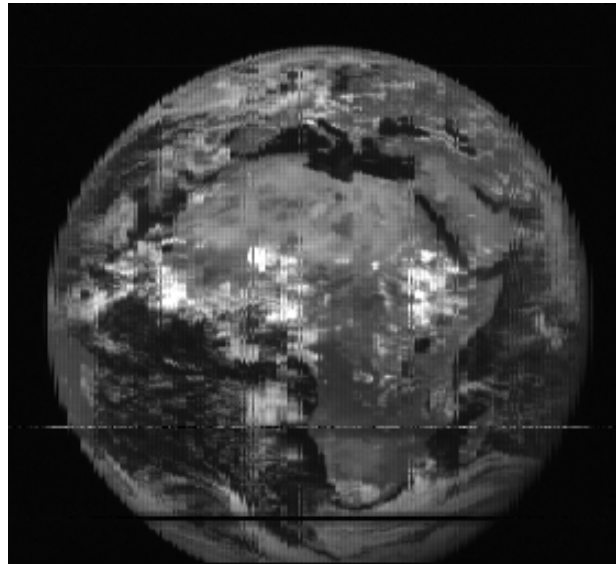
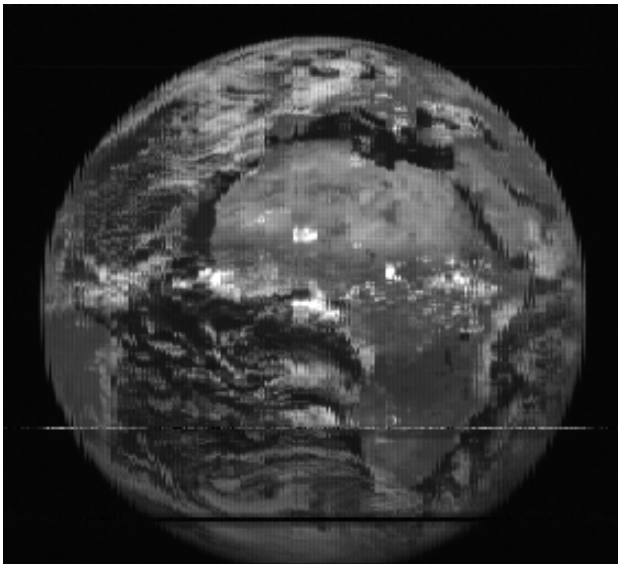
MSG-1 GERB-2 Move to 41.5°E



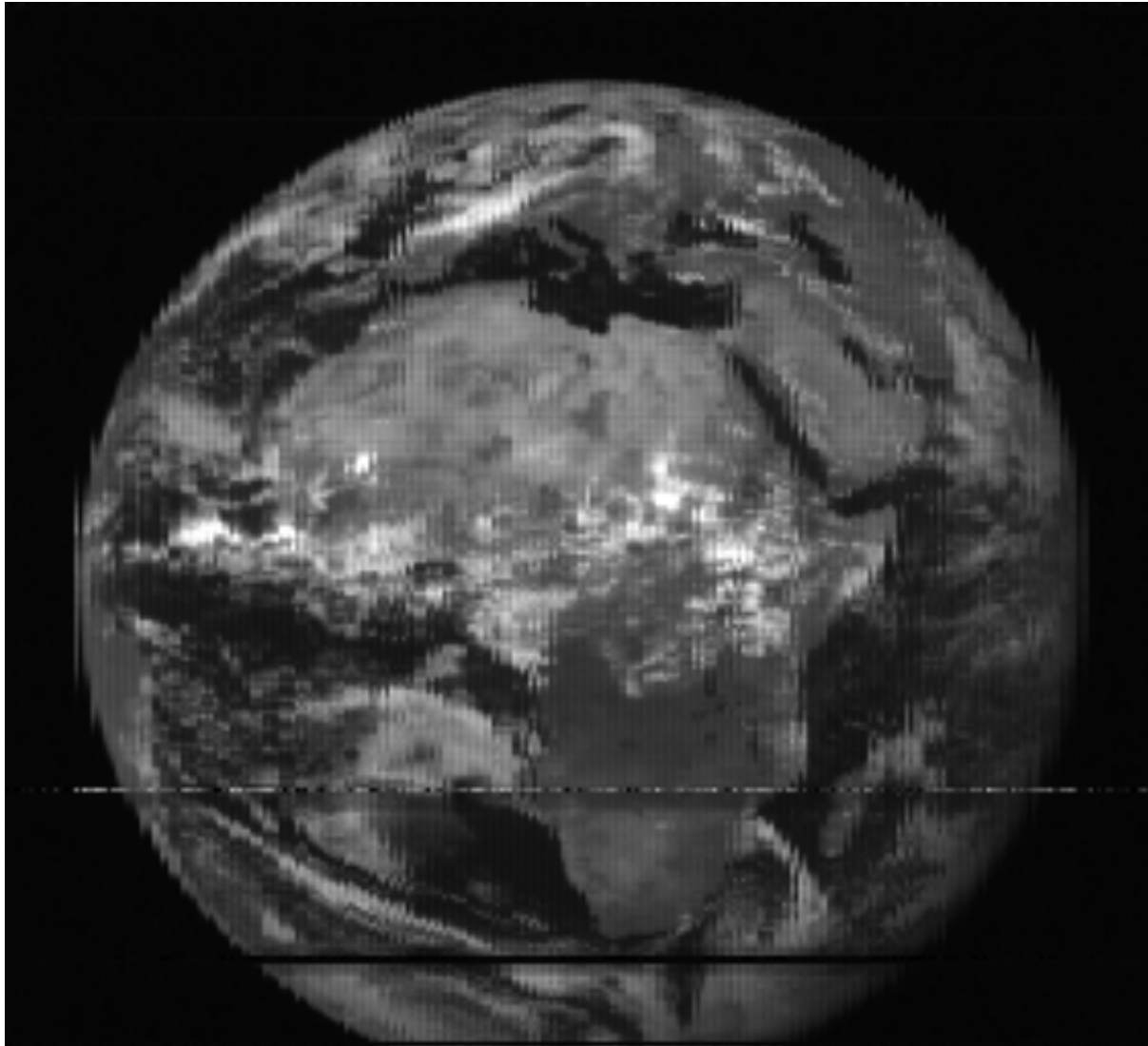
MSG-1 GERB-2 Move to 41.5°E – GERB Images

GERB-2 Imaging during the drift:

1 st July	10:30-13:30	NORMAL	3.6°E
1 st July	13:30-14:15	CALMON	3.6°E
27 th -28 th Jul	9:00-12:00	NORMAL	13.8°E
4 th -5 th Aug	9:00-12:00	NORMAL	17.5°E



MSG-1 GERB-2 Move to 41.5°E – GERB Images on ESU



Future

GERB-3

- Continue as prime instrument
- Investigate automation of recovery from as many mirror incidents as possible

GERB-4

- Activation sequence
 - Jan/Feb 2017 MSG-4 payload activation
 - July/Aug 2017 MSG-4 payload activation (SEVIRI?)
 - Jan/Feb 2018 MSG-4 possibly brought out of storage

GERB-1

- Final part of DSM testing is to execute GSMWELLY command
- Short burst of boost to maximum nominal torque

GERB-2

- Return to imaging on the 26th October (on SSU)